

Distributed Power System Research Center

Grid-Forming Inverter-based Distributed Control for Microgrids

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Outline

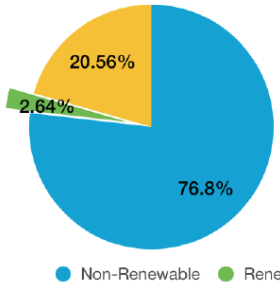
- **Introduction**
- **GFM Inverter Control Strategy**
- **Distributed Control Strategy**
- **Experimental Results**
- **Conclusion**



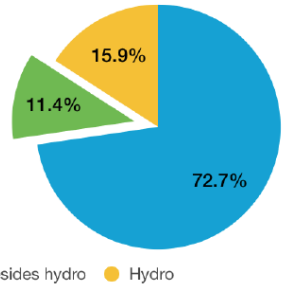


Power Grid Transformation

Renewable Energy Share- end 2004

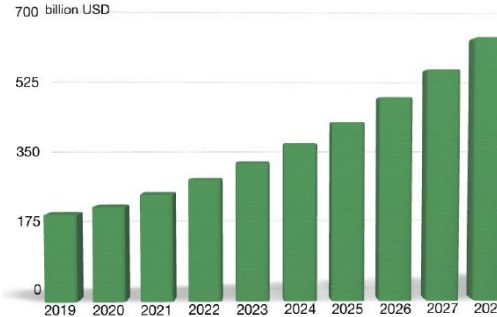


Renewable Energy Share- end 2019

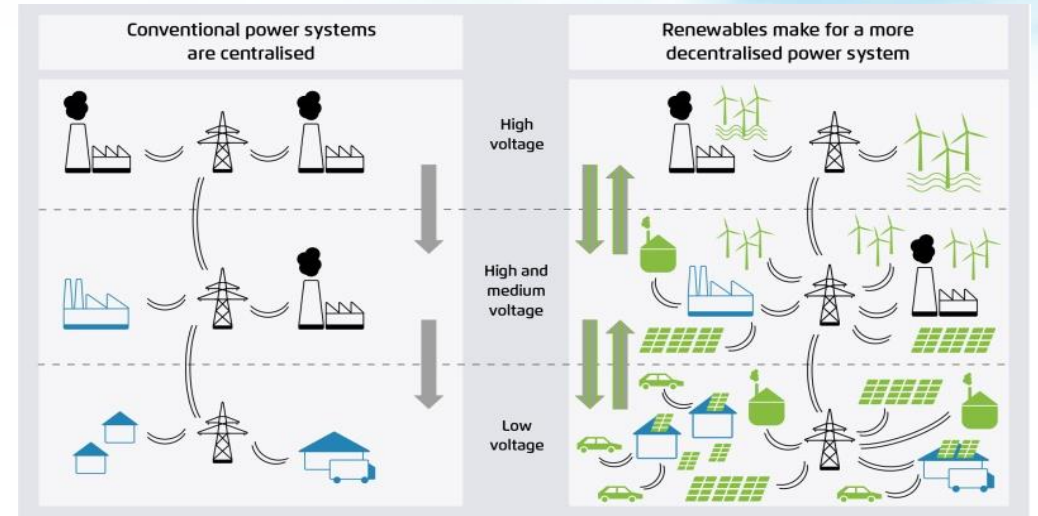


● Non-Renewable ● Renewable besides hydro ● Hydro

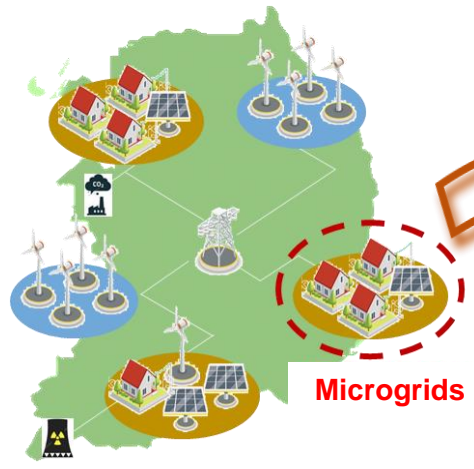
<Renewable energy share of global electricity production in 2004 vs 2019>



<Projected global DER market growth>

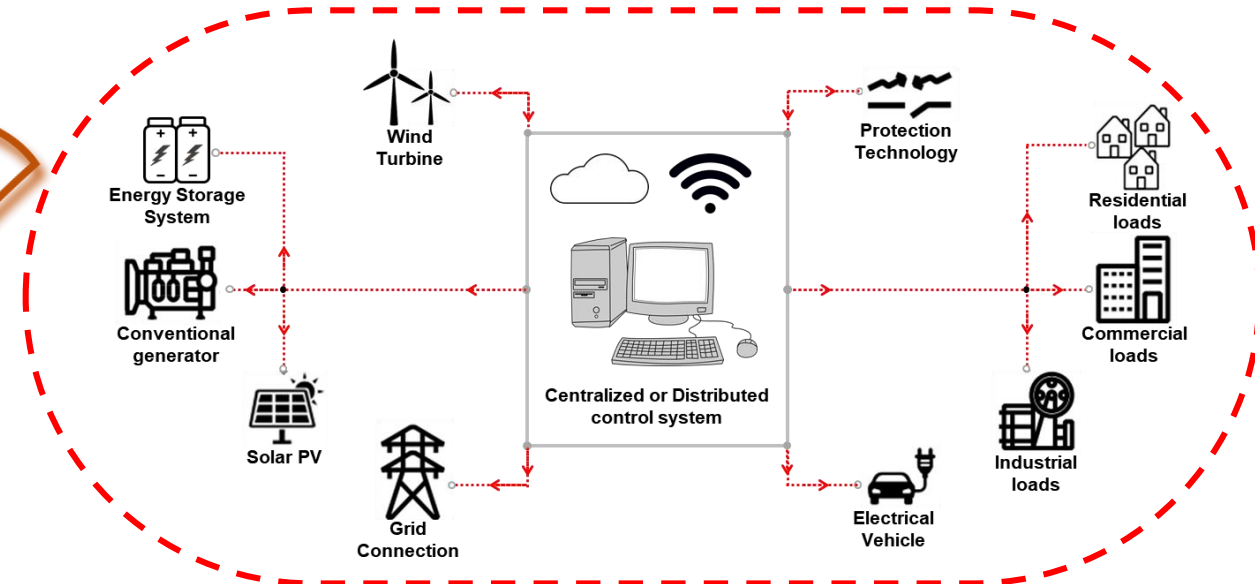


Present



Future

Microgrids



[Ref.] Grid Forming Inverter_EPRI Tutorial, 2022.



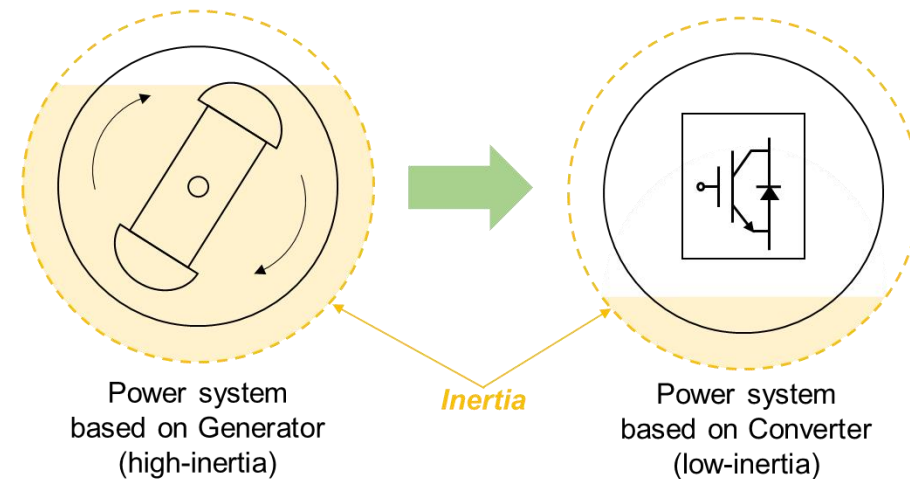
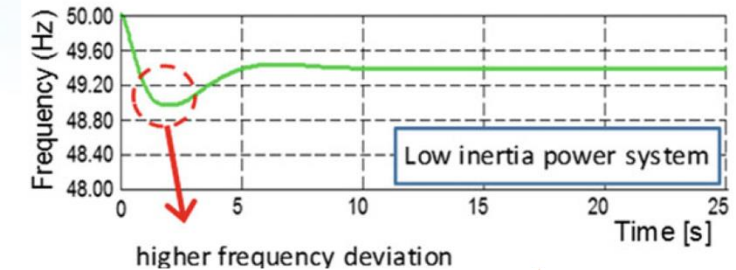
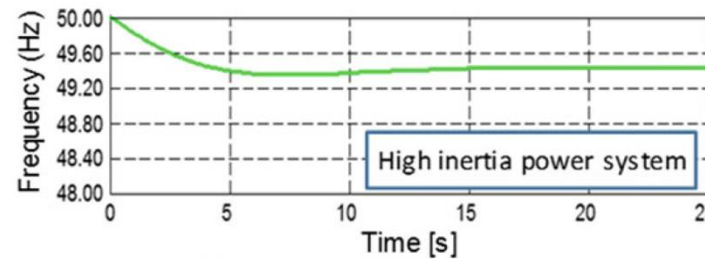
Frequency Stability Issues

**Reduction in system inertia
(Replacement of SG with IBR)**

**Reduced time to respond to
frequency changes**

Increased UFLS activation

**Increased possibility of
blackouts due to protective relay
activation**

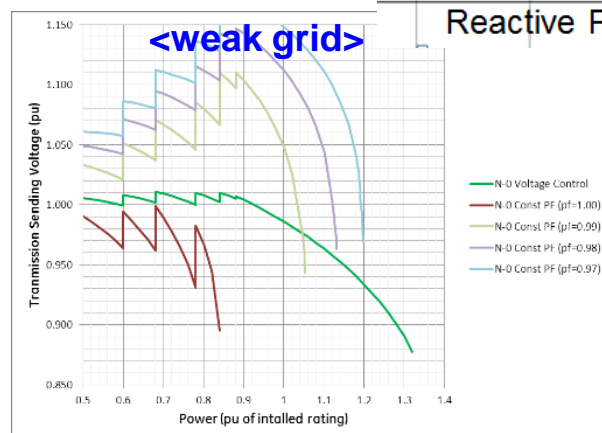
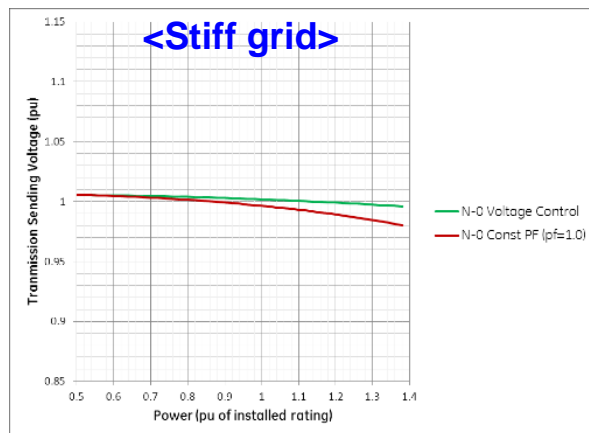


- ✓ In Ireland, Texas, and South Australia, where IBR penetration is high, frequency stability problems occur during certain times of the day.
- ✓ Small island power systems such as New Zealand and Hawaii already face low inertia-related challenges.

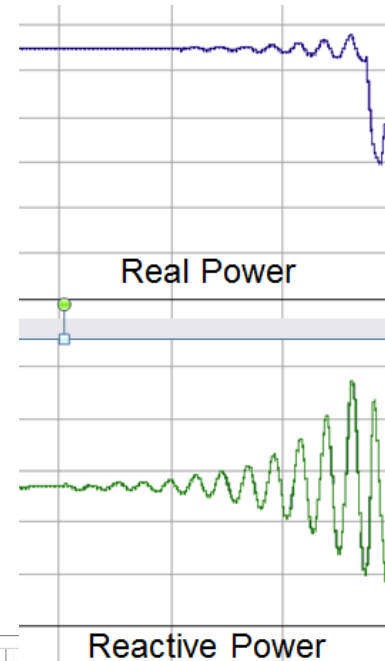
Stability Issues in Weak Grids

- ❖ Failure to ride through disturbances
- ❖ Converter control interactions
- ❖ Converter control instability
- ❖ Cycling between converter control modes
- ❖ Steady-state voltage collapse and power transfer

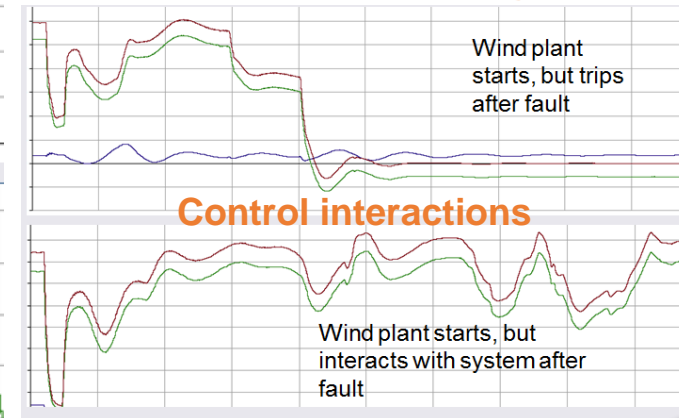
Quasi-steady state voltage collapse



Control instability

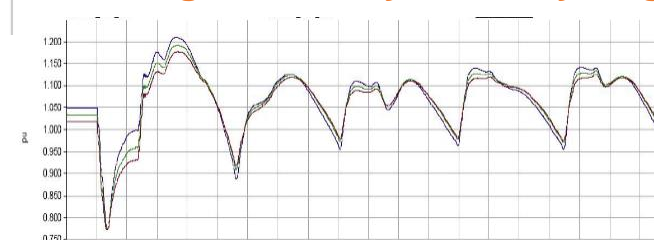


Failure to ride through

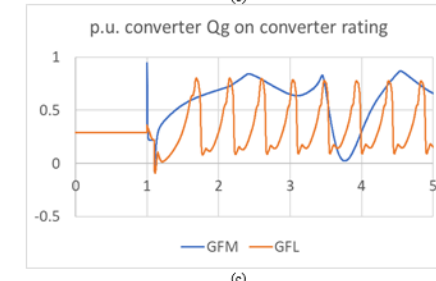
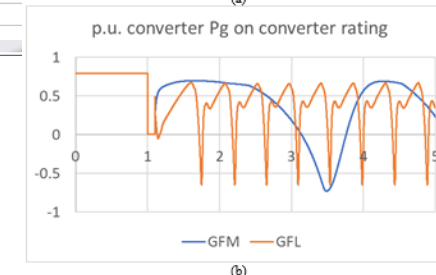
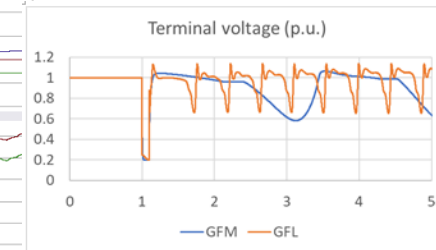


Control interactions

Voltage instability due to cycling

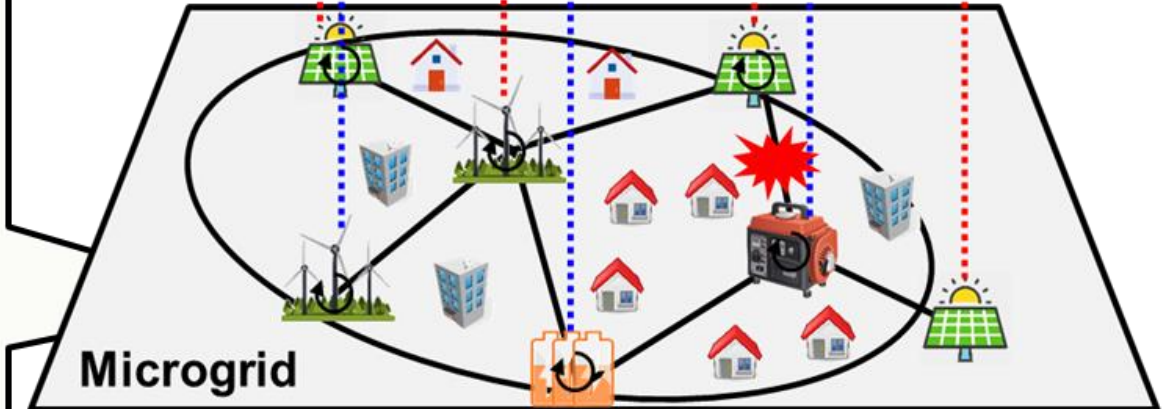
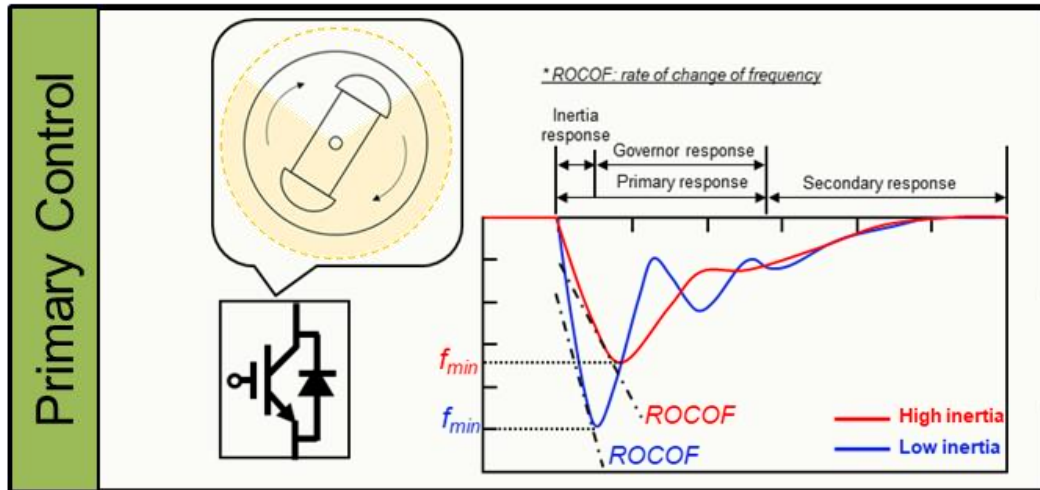
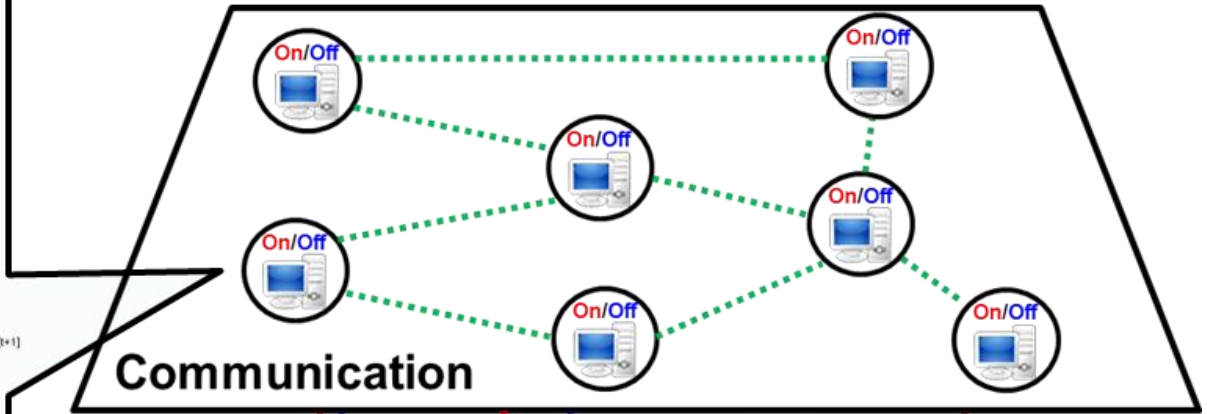
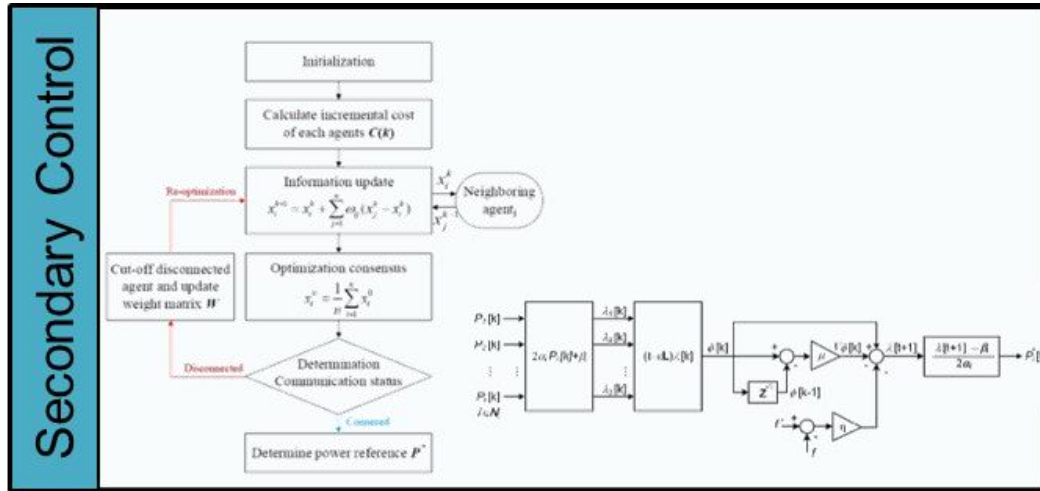


Unstable recovery due to network transfer limits



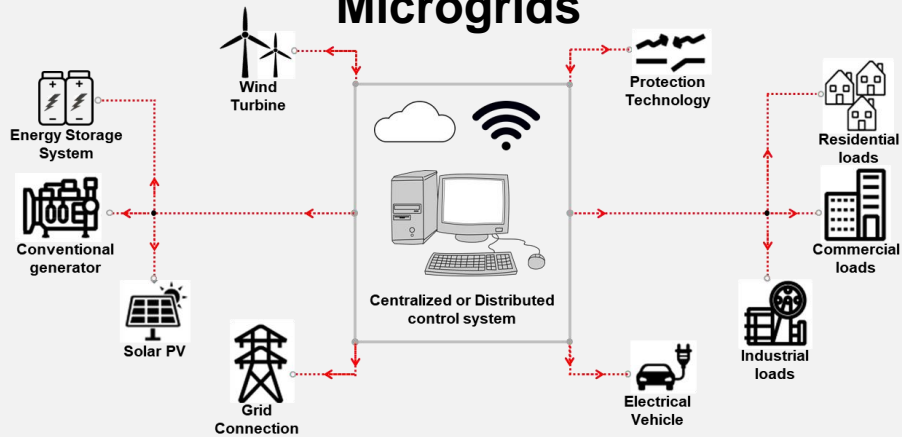


- ❖ GFM-based virtual inertia control technology – improving frequency stability
- ❖ Distributed operation – Operation system without Central EMS



Development of GFM-based inverter and distributed operation technology for IBR to improve stability and resiliency

Microgrids

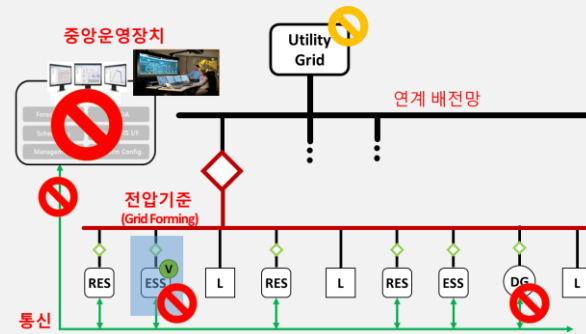


현재 전력계통



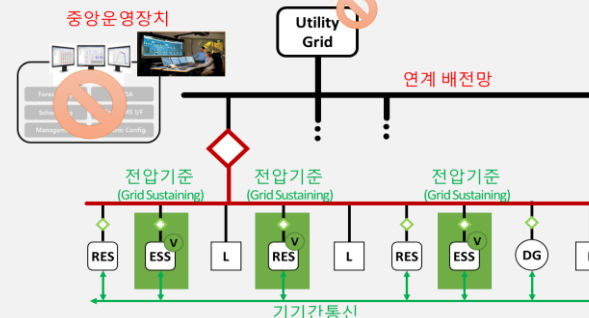
미래 전력계통

Conventional Microgrids

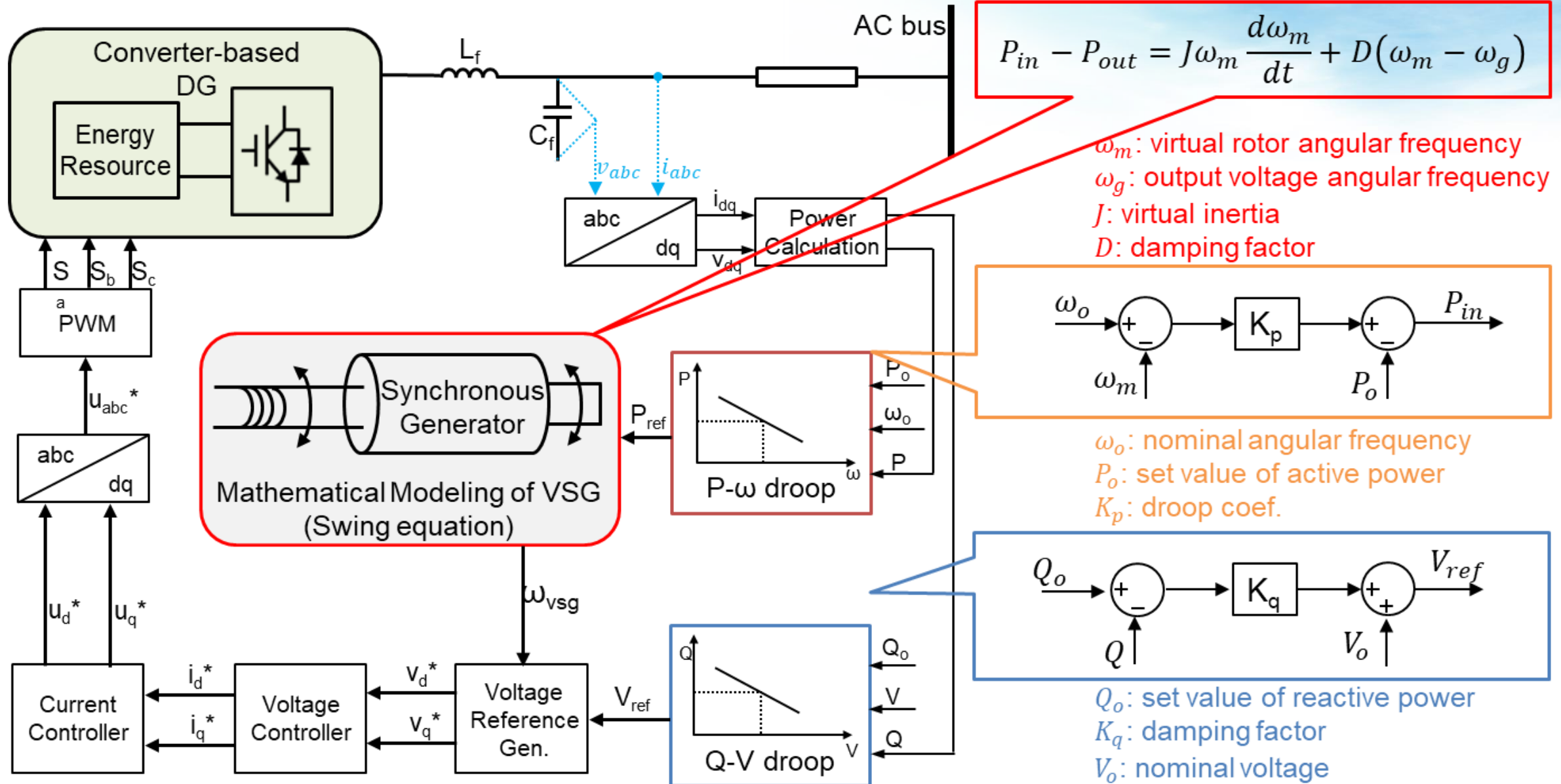


- Centralized EMS
- Single grid-forming source (e.g. diesel, CVCF ESS)
- Grid-following inverter-based resources
- Requires complex infrastructure and communication
- It has a single point of failure, as a malfunction in the central controller can disrupt the entire system

Advanced Microgrid (Proposed technology)



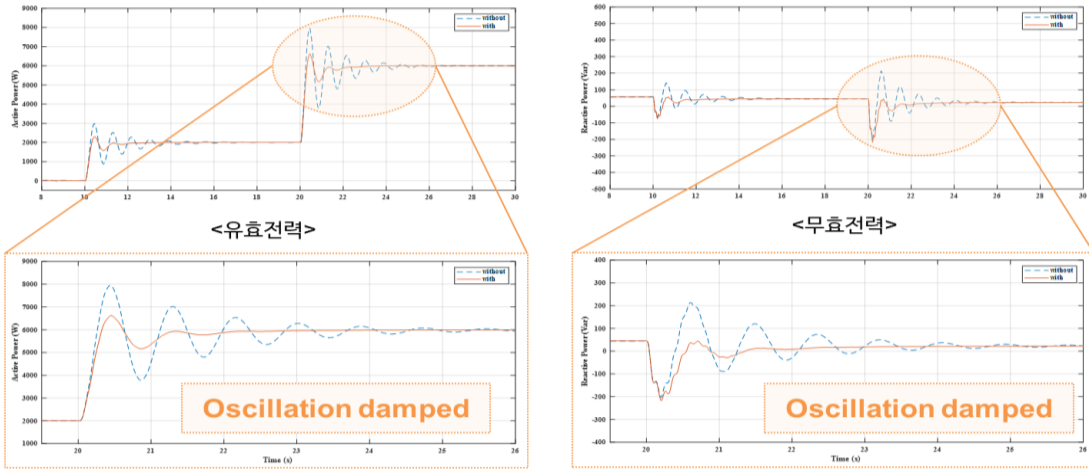
- Distributed Operation without Centralized EMS
- Multiple grid-forming inverter-based resources
- More flexibility and scalability
- More reliable as there is no single point of failure
- Lower initial setup and operational costs



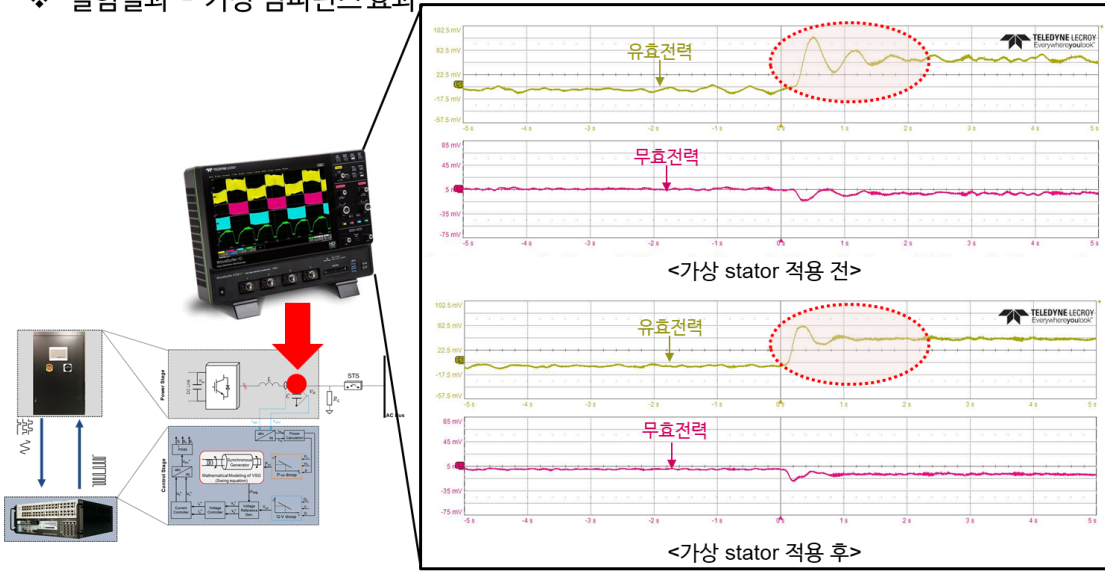
Test of GFM-based VSG(H/W)

❖ Grid-connected Mode

▪ PQ control

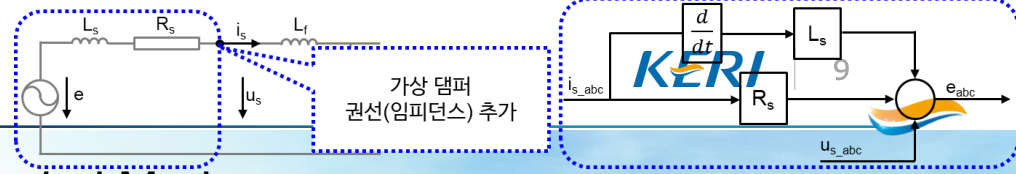
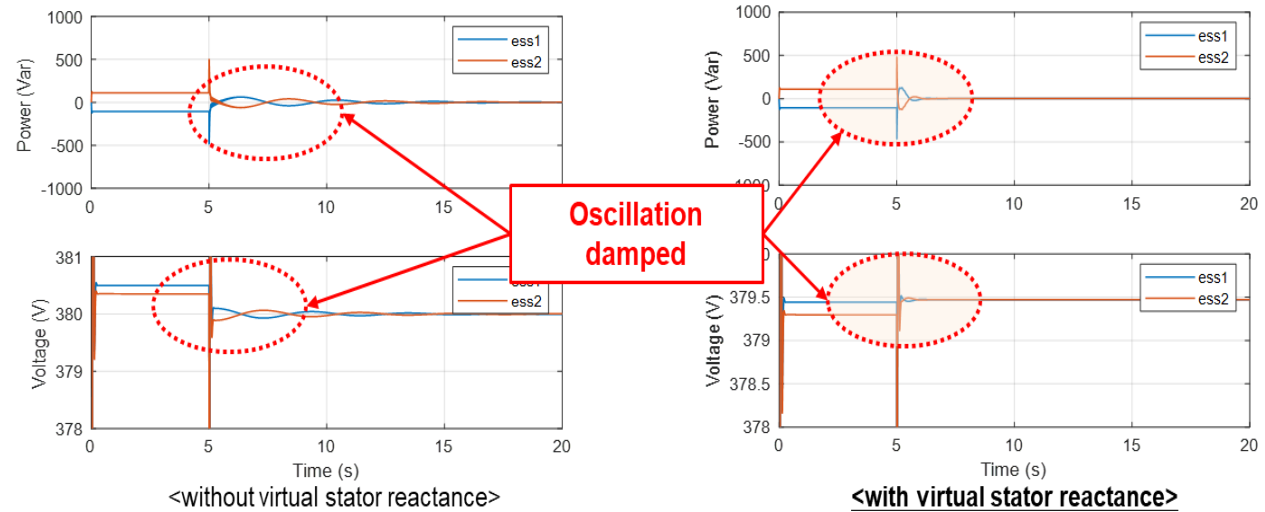
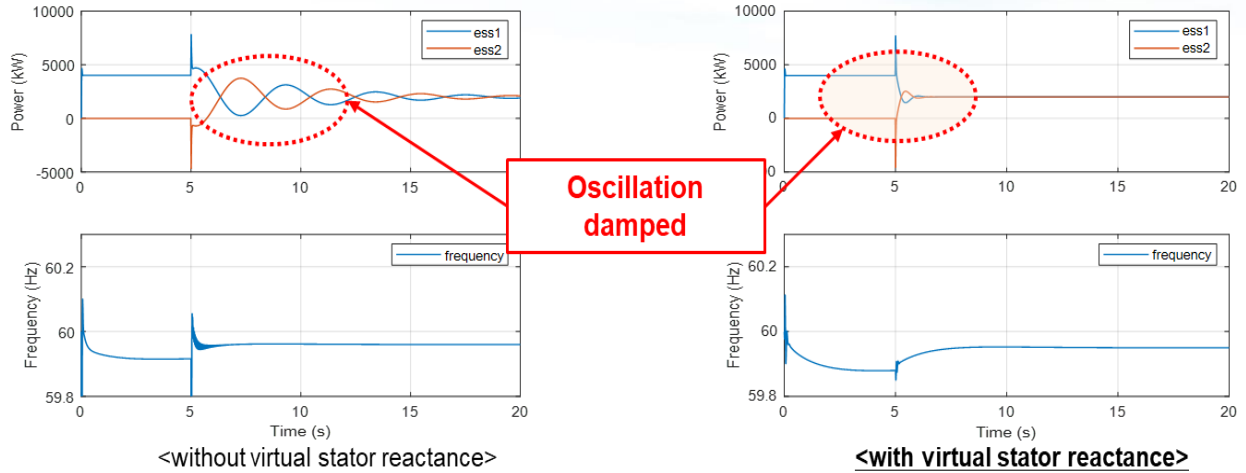


❖ 실험결과 - 가상 임피던스 효과



❖ Islanded Mode

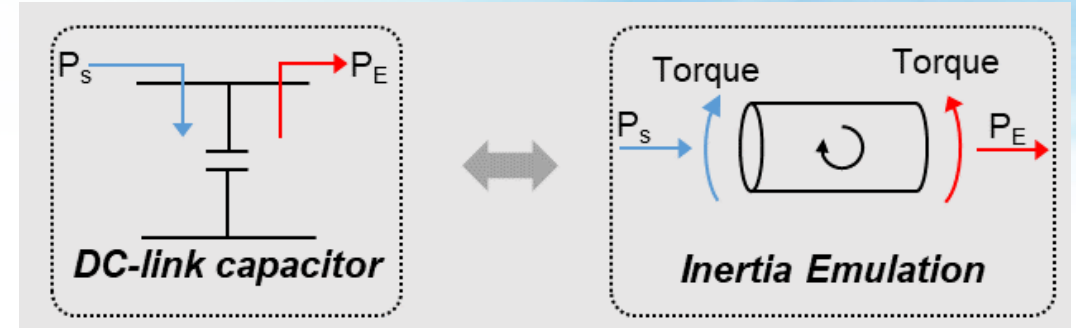
▪ Voltage & Frequency control



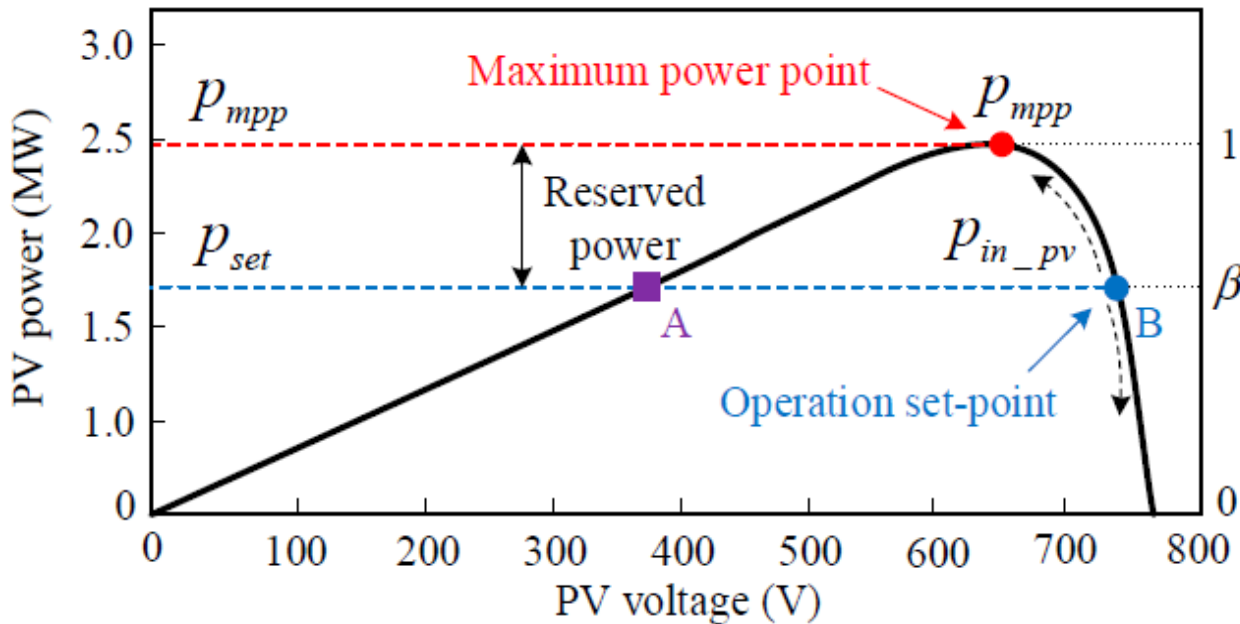
GFM Control Strategy for PV-Inverter

❖ Classification of control strategy for PV-inverter

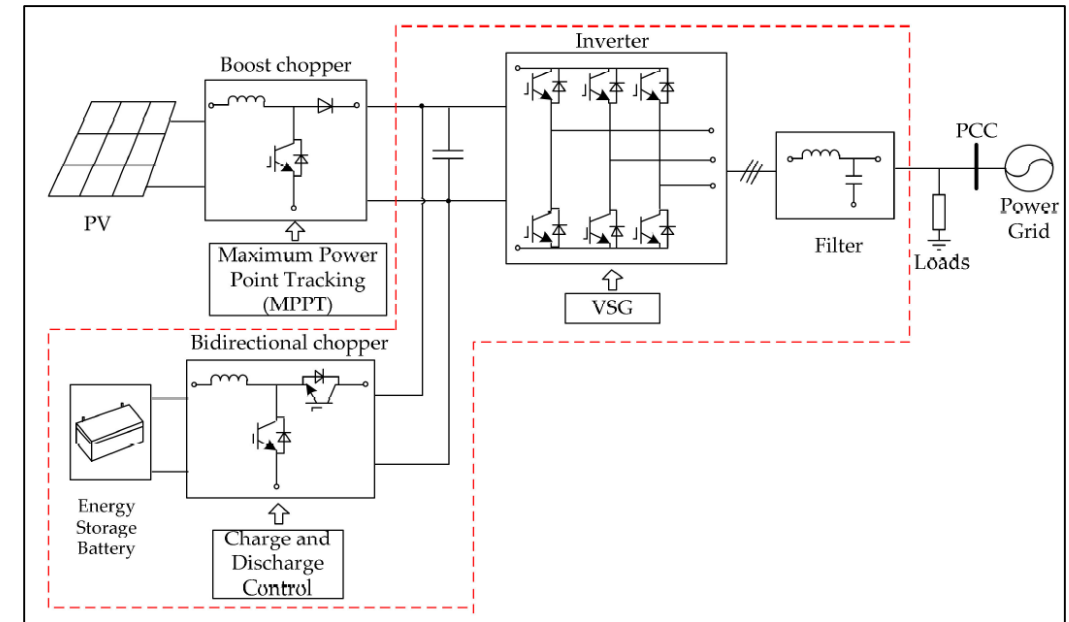
- DC link capacitor
- Energy storage system
- MPPT curve



<Virtual inertia using cap.>



<Virtual inertia using MPP characteristic>



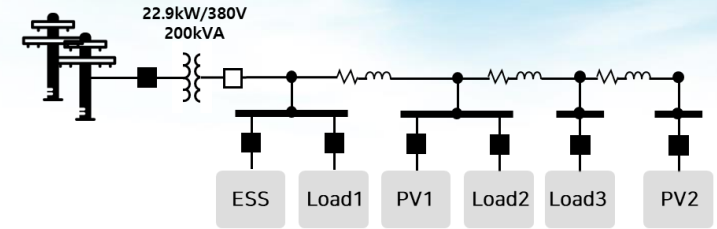
<Virtual inertia using additional ESS>



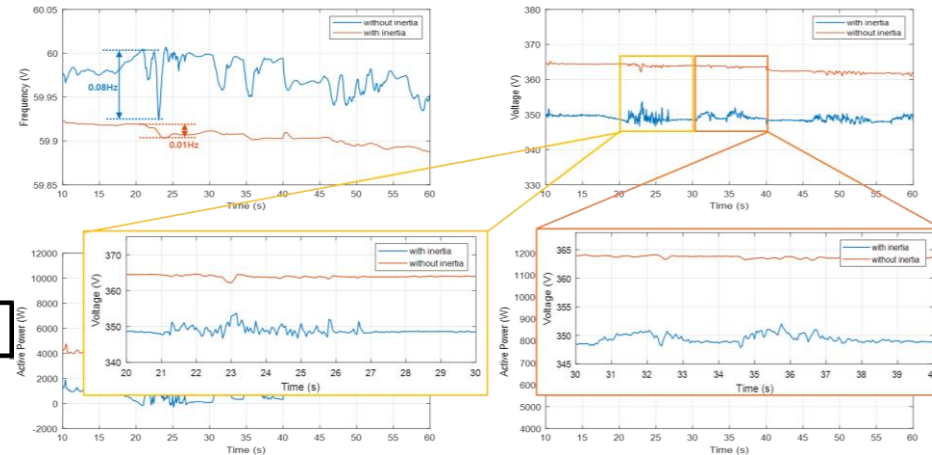
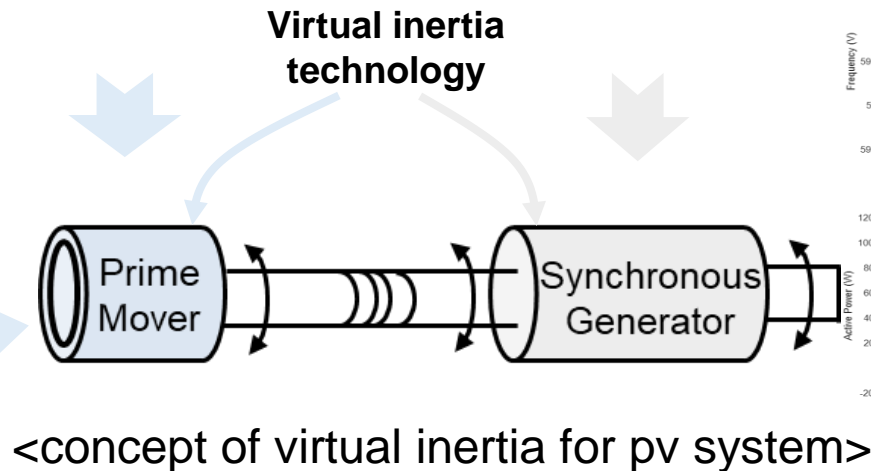
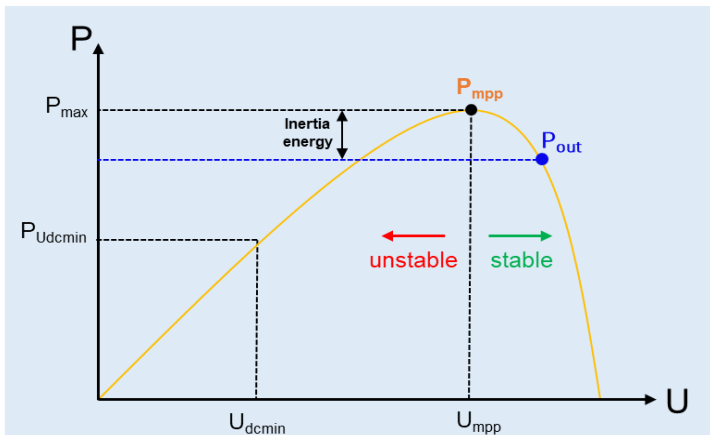
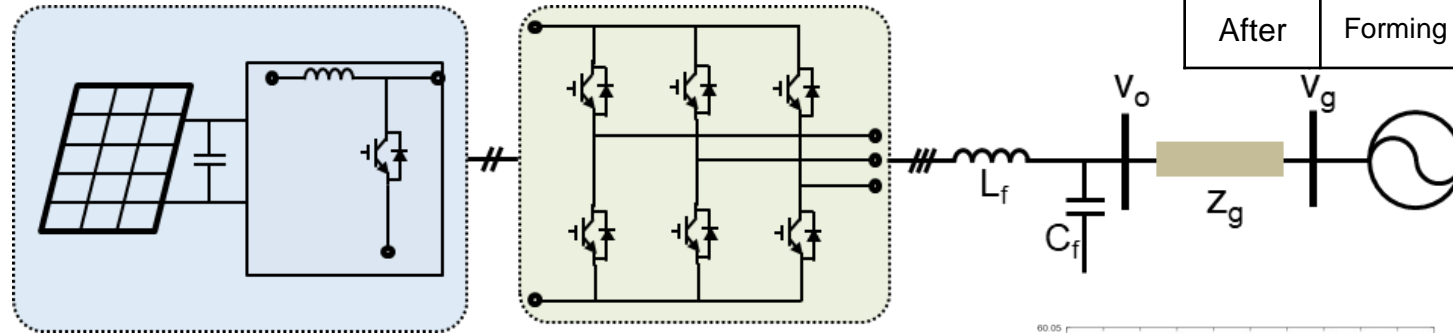
Virtual Inertia Technology for PV system

❖ PV system – DC/DC converter + AC/DC converter

- DC/DC converter: Prime mover
- AC/DC converter: Synchronous generator

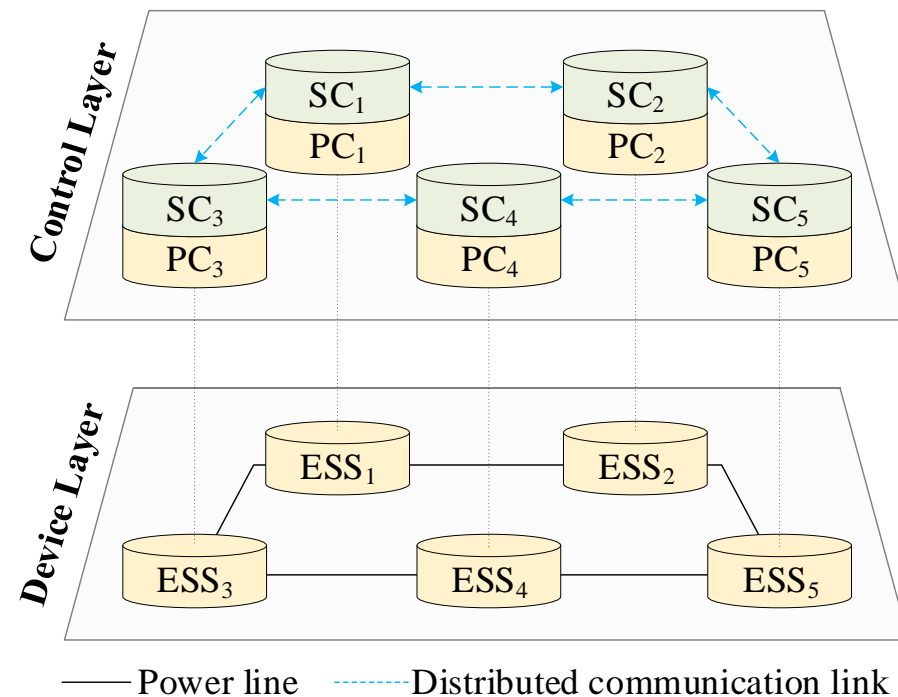
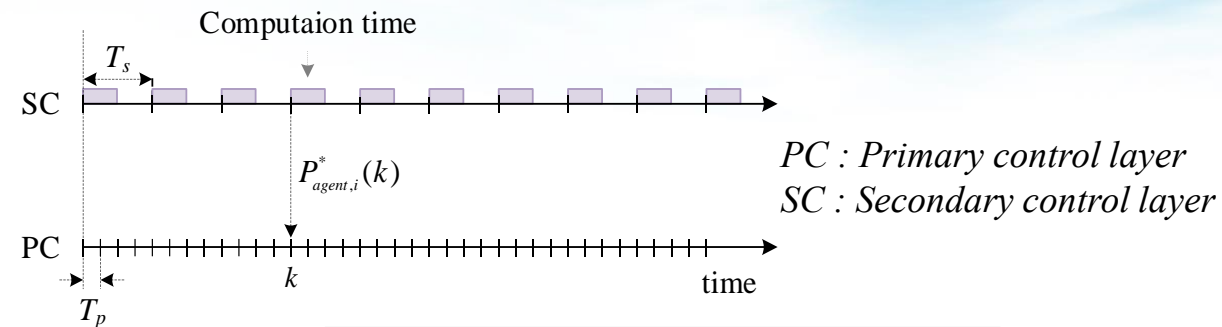
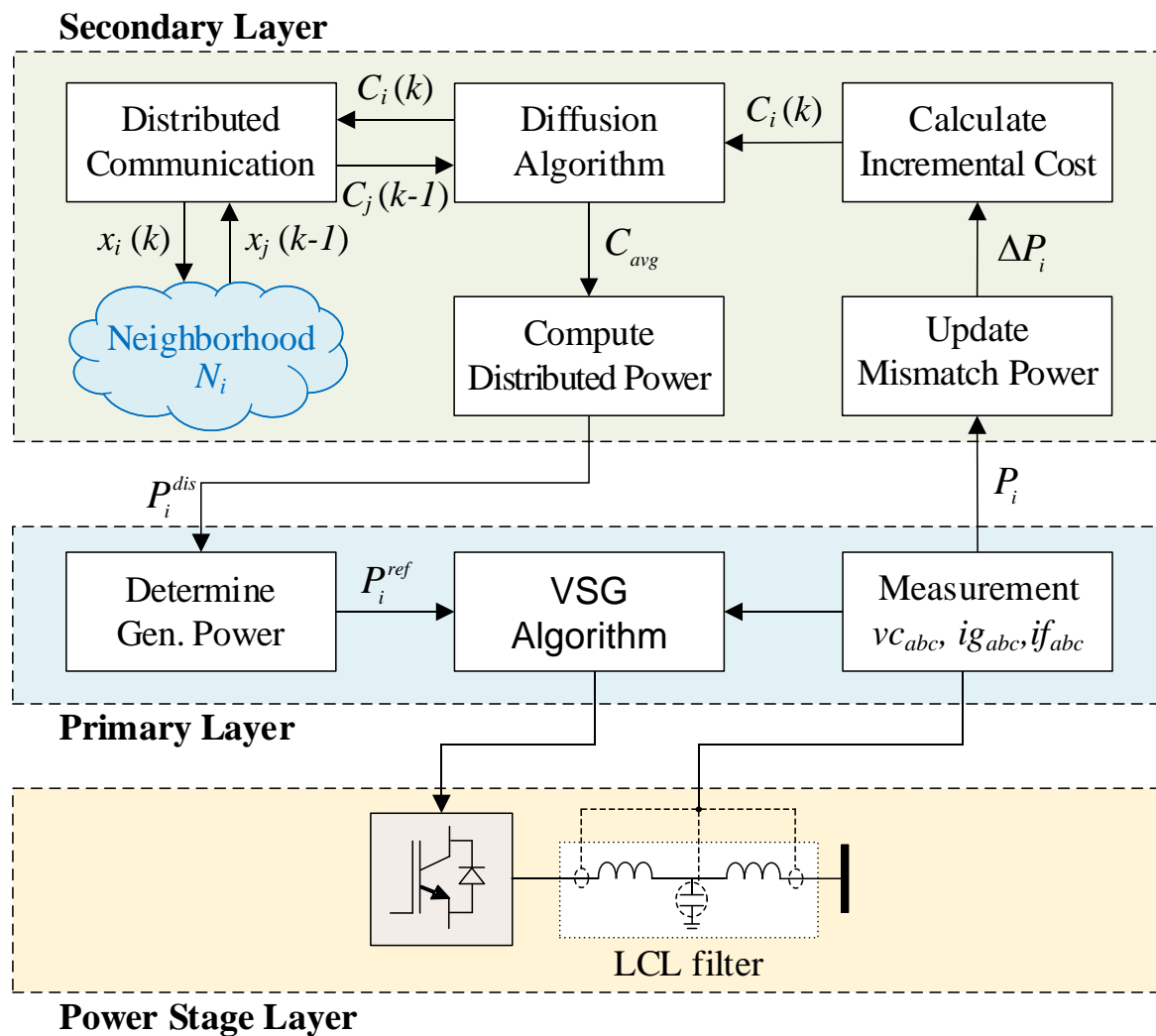


Before	Forming	MPPT	MPPT
After	Forming	Forming	Forming





Hierarchical Control for MG



<Distributed control layer>

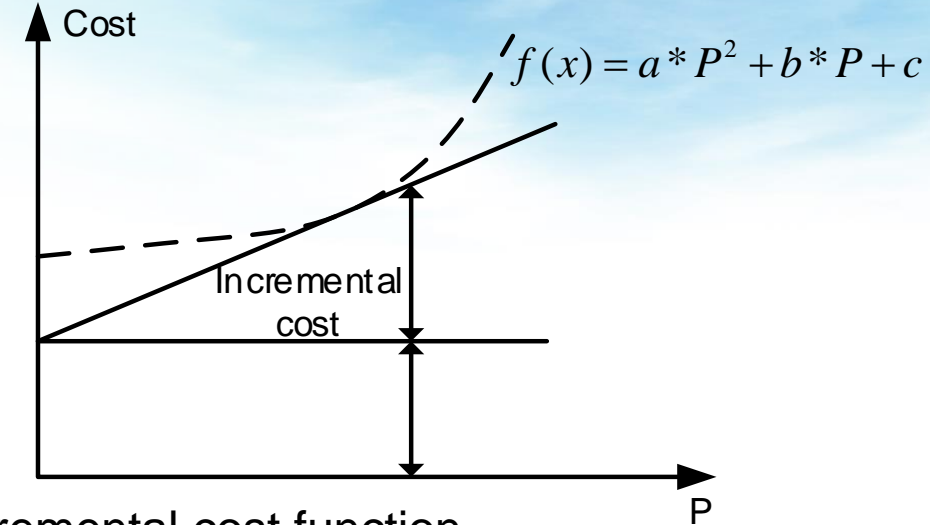
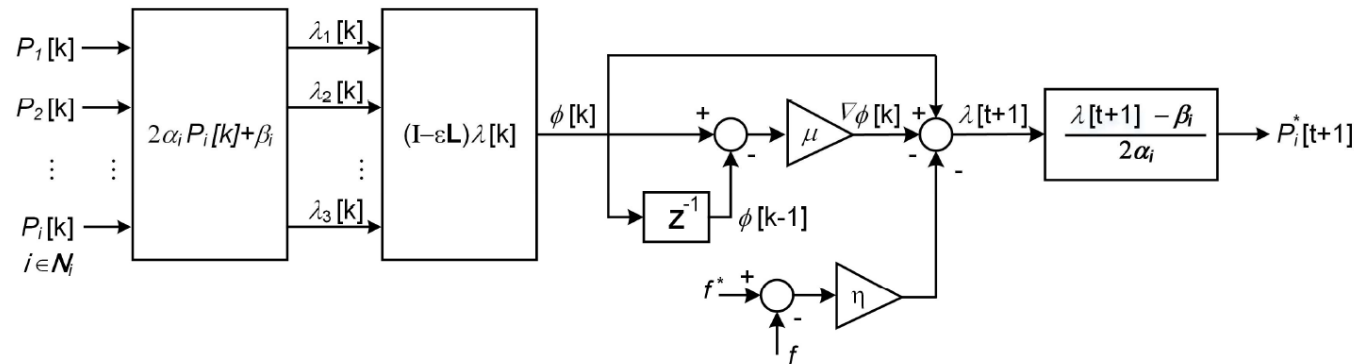
❖ Distributed control algorithm based on diffusion algorithm

▪ Cost function

$$C_e(P_e^{ESS}) = \alpha_e^{ESS} (P_e^{ESS} + 3P_{e,max}^{ESS} \cdot (DOD))^2 + \beta_e^{ESS} (P_e^{ESS} + 3P_{e,max}^{ESS} \cdot (DOD)) + \gamma_e^{ESS}$$

▪ Diffusion algorithm considering frequency restoration

$$\begin{cases} \Phi[k] = (I - \varepsilon L)\lambda[k] \\ \lambda[k+1] = \Phi[k] - \mu \nabla \Phi_v[k] - \eta (f^* - f) \end{cases}$$

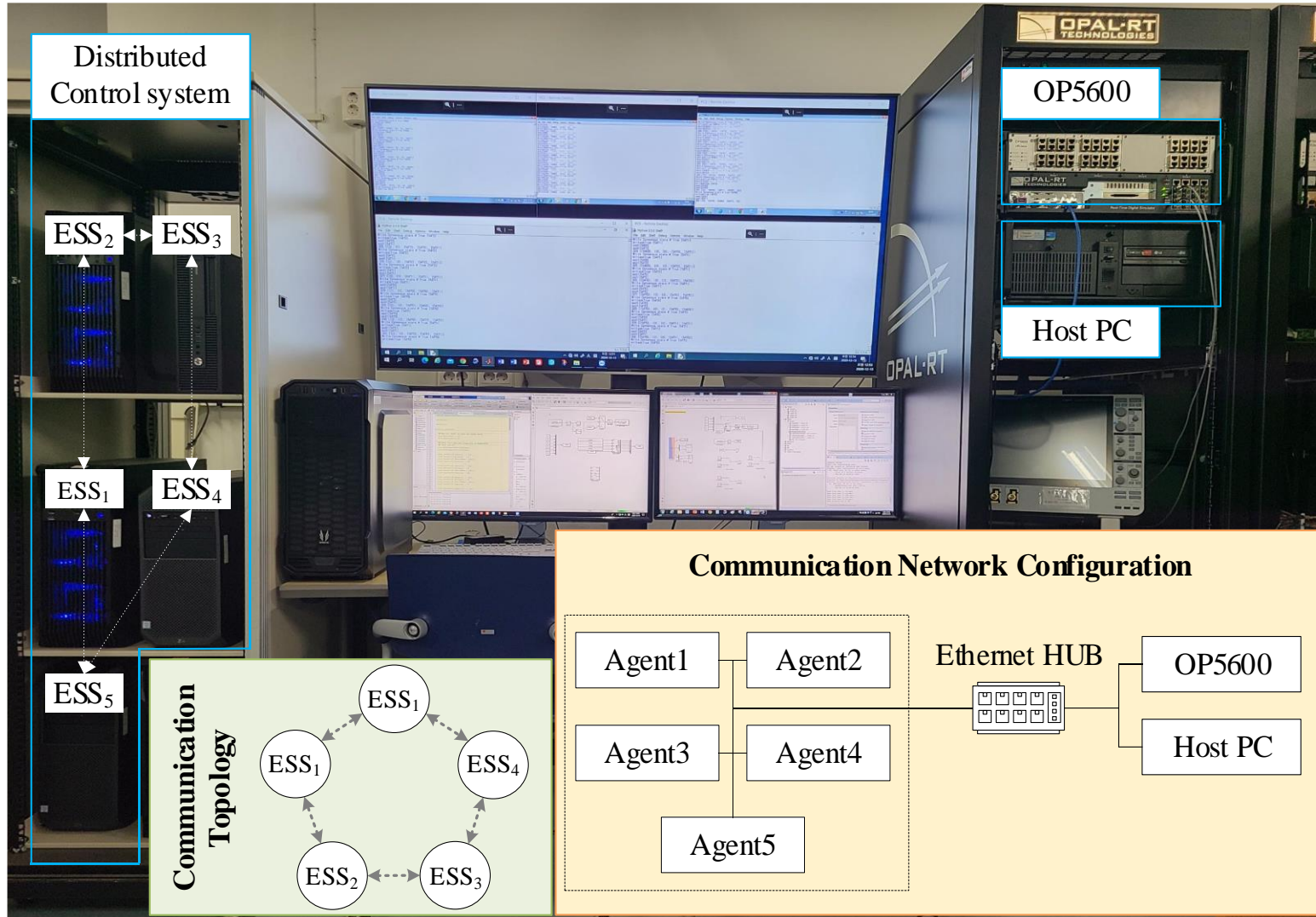


▪ Incremental cost function

$$\frac{\partial C_e(P_e^{ESS})}{\partial P_e^{ESS}} = 2\alpha_e^{ESS} (P_e^{ESS} + 3P_{e,max}^{ESS} \cdot (DOD)) + \beta_e^{ESS}$$

- P_e : Electrical Power
- $P_{e,max}$: Max. Power
- α, β, γ : battery coefficient
- DOD : Depth of discharge

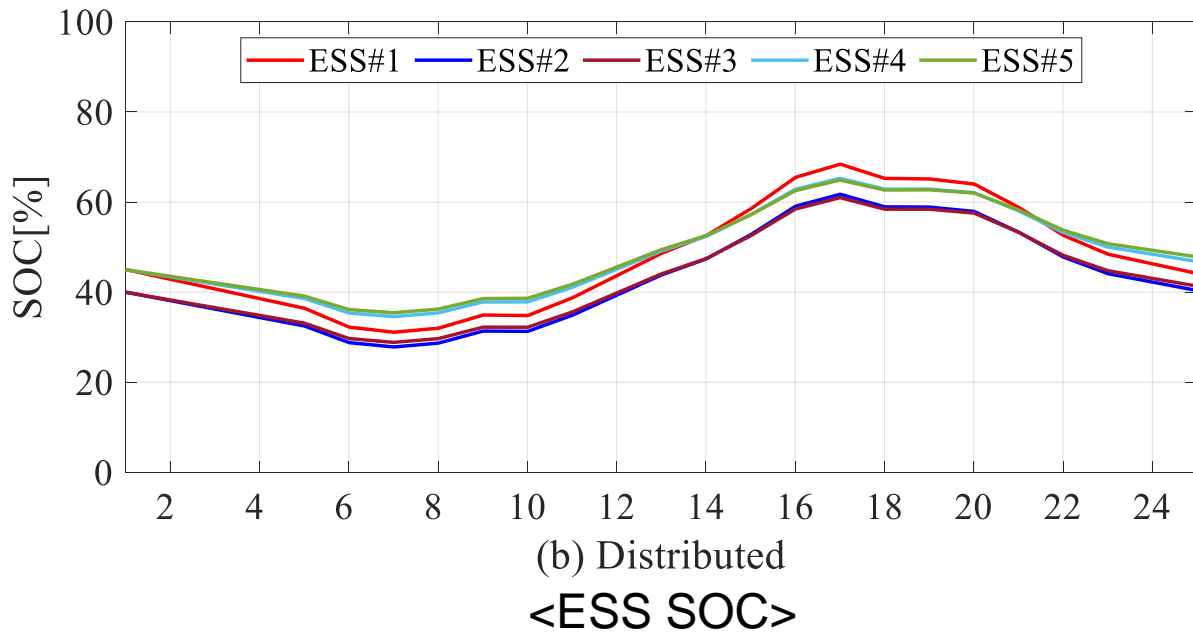
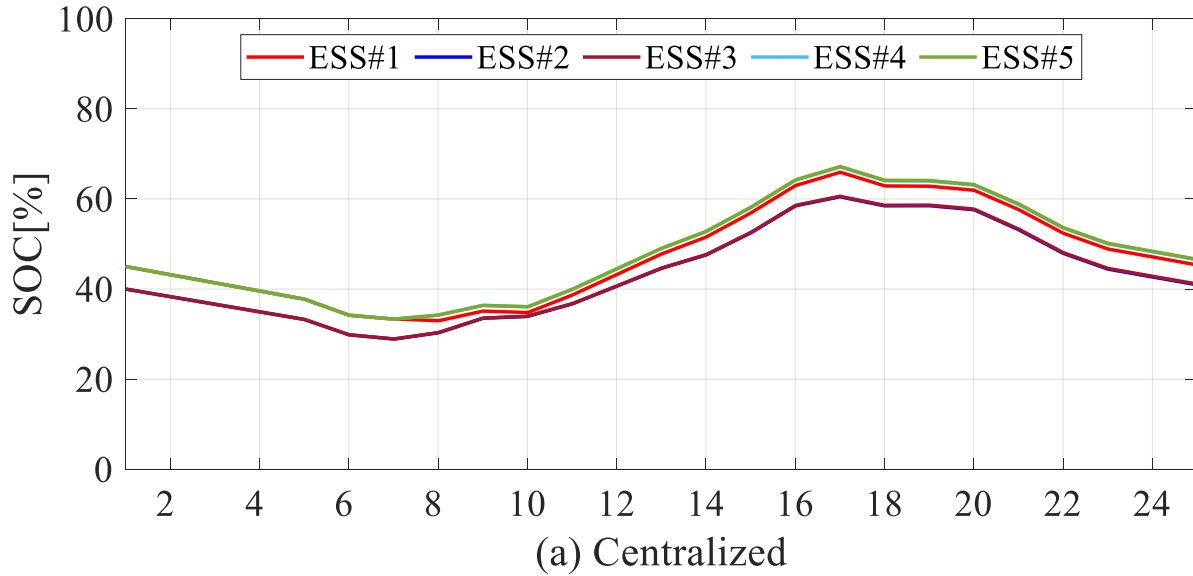
❖ Distributed control technology for microgrids



Agent	A_i (\$/kW ₂ H)	β_i (\$/kWh)	γ_i (\$/kWh)
ESS ₁	0.001562	3.95	213
ESS ₂	0.00174	3.99	234
ESS ₃	0.00186	4.02	246
ESS ₄	0.00196	4.05	270
ESS ₅	0.00208	4.09	283

Symbol	PARAMETER	Value
T_s	Sampling time	50 μ s
T_{com}	Communication time	0.1 s
T_{EMS}	EMS command time	30 s
k_{sp}, k_{si}	PI gains of secondary controller	0.01, 6

Centralized vs distributed control

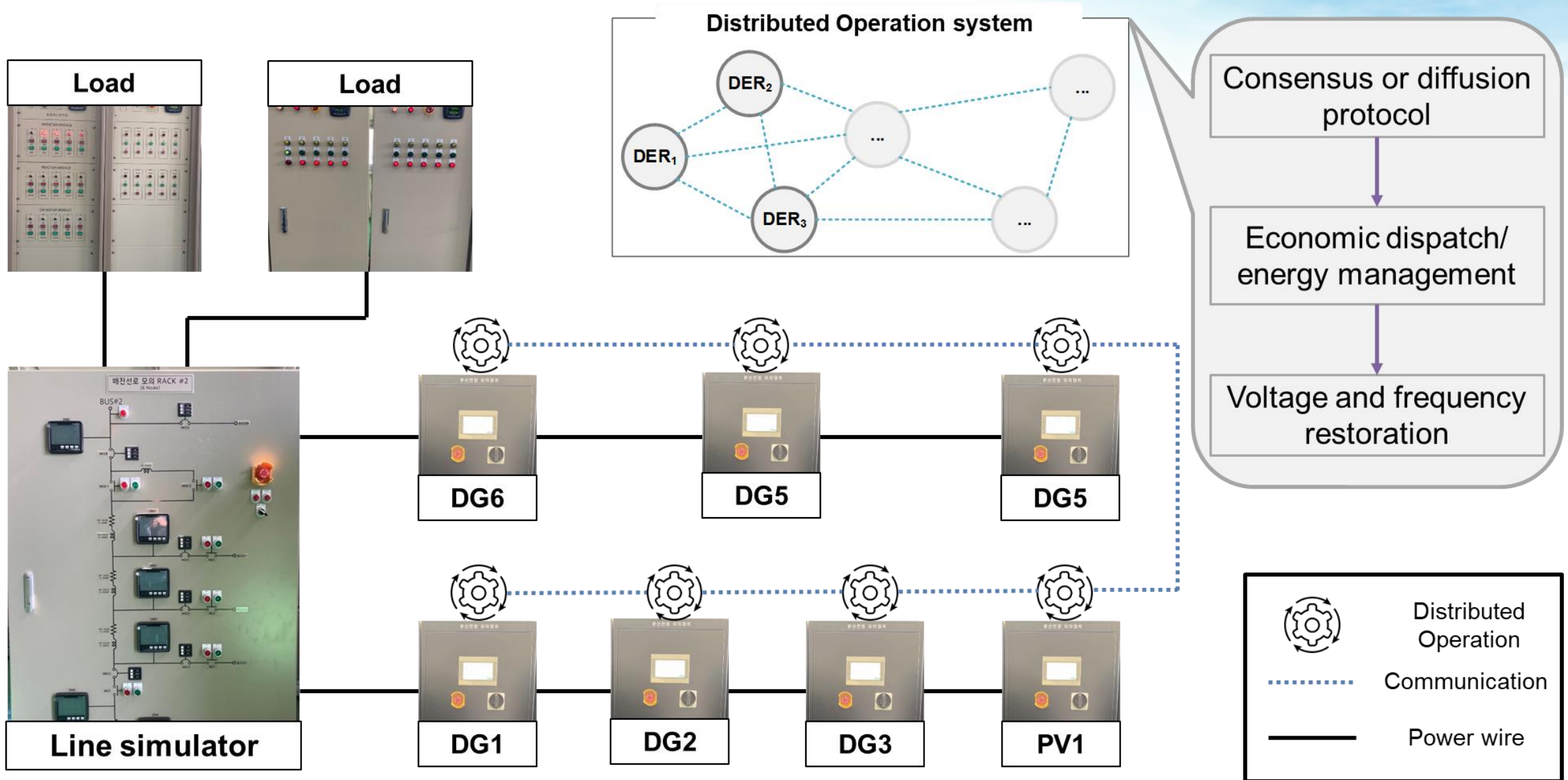


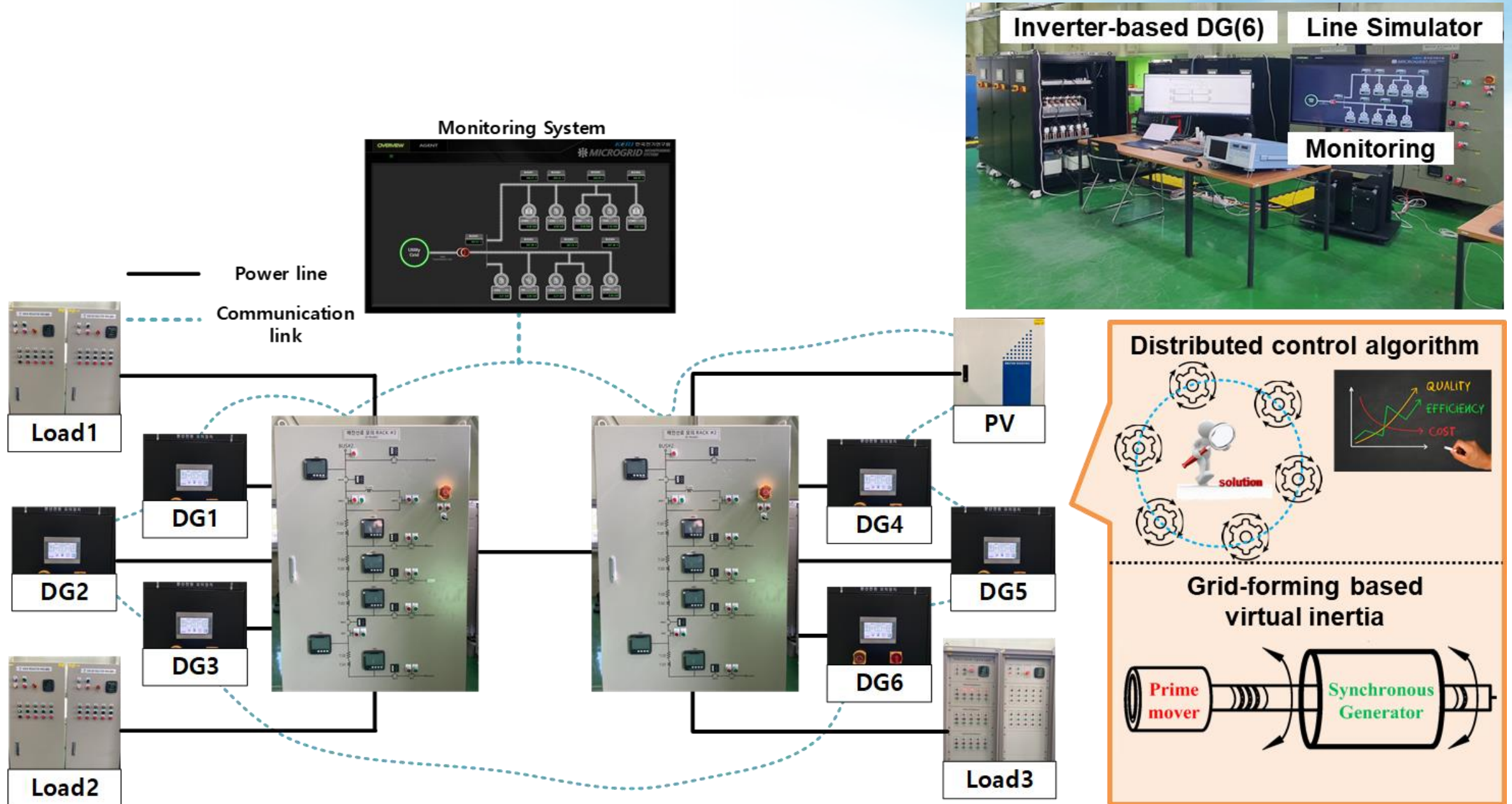
중앙집중식 제어방법과 유사한 SCO 패턴을 보임
 운영비용의 경우 중앙집중식 대비 약 90% 성능을 보임

Control Scheme	Total Generation Cost
Centralized EMS	\$ 766.8190
Proposed method	\$ 808.5974
Difference	5.1668%

<ESS SOC>

Pilot Plant (1)





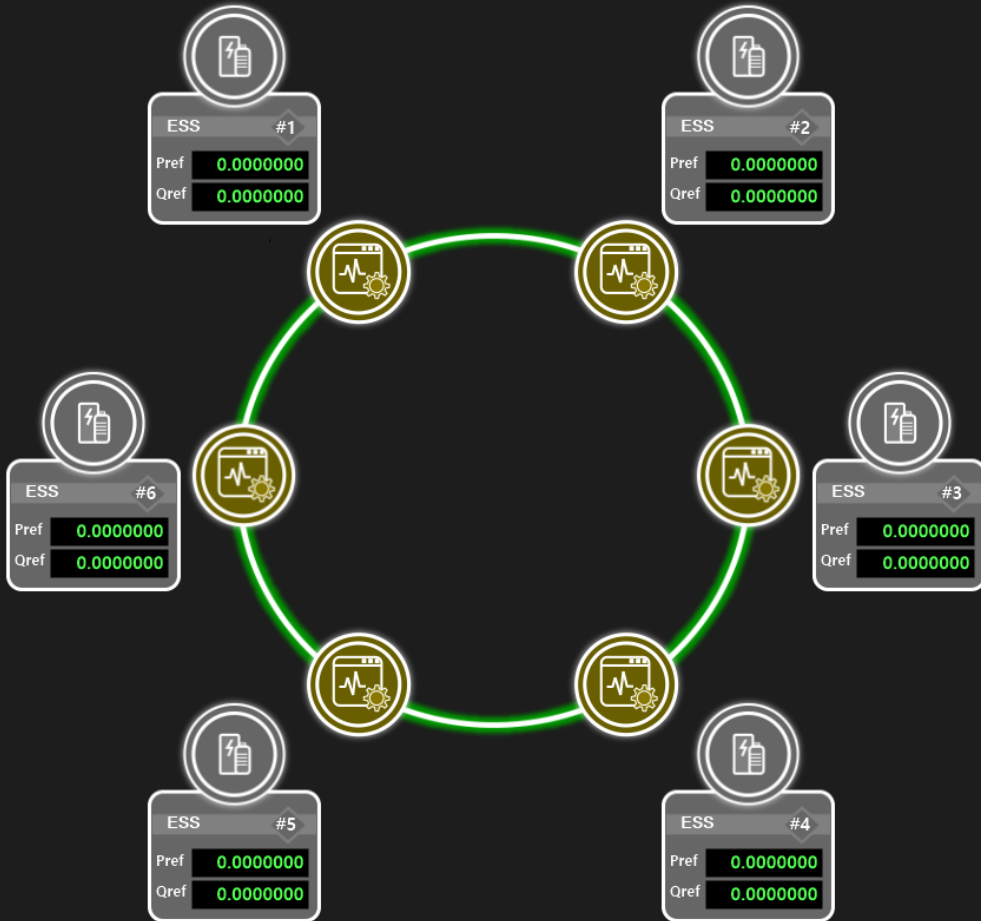


OVERVIEW

AGENT

KERI 한국전기연구원

MICROGRID MONITORING SYSTEM



Agent 1

Input	
P	0.0000000
Q	0.0000000
SOC	0.0000000
P1	0.0000000
Q1	0.0000000
SOC1	0.0000000
P2	29.2035580
Q2	23.6739635
SOC2	69.8095016
Output	
Pref	0.0000000
Qref	0.0000000

Agent2

Input	
P	29.2035580
Q	23.6739635
SOC	69.8095016
P1	0.0000000
Q1	0.0000000
SOC1	0.0000000
P2	-33.3886681
Q2	-23.5583572
SOC2	69.8082657
Output	
Pref	0.0000000
Qref	0.0000000

Agent3

Input	
P	-33.3886681
Q	-23.5583572
SOC	69.8082657
P1	29.2035580
Q1	23.6739635
SOC1	69.8095016
P2	13.3673353
Q2	8.2450142
SOC2	69.8814850
Output	
Pref	0.0000000
Qref	0.0000000

Agent4

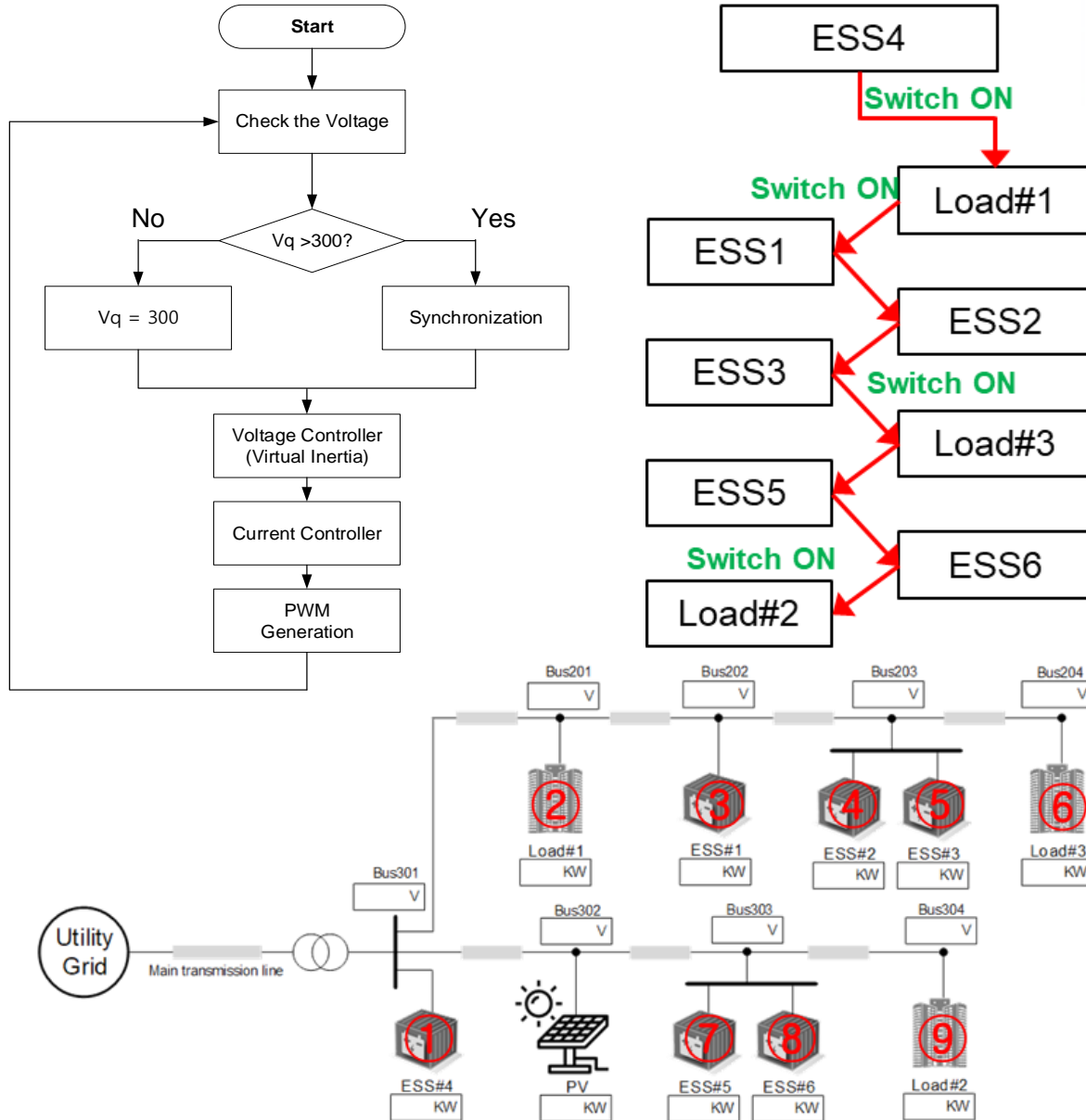
Input	
P	13.3673353
Q	8.2450142
SOC	69.8814850
P1	-33.3886681
Q1	-23.5583572
SOC1	69.8082657
P2	-3.2787592
Q2	43.5659981
SOC2	69.7629623
Output	
Pref	0.0000000
Qref	0.0000000

Agent5

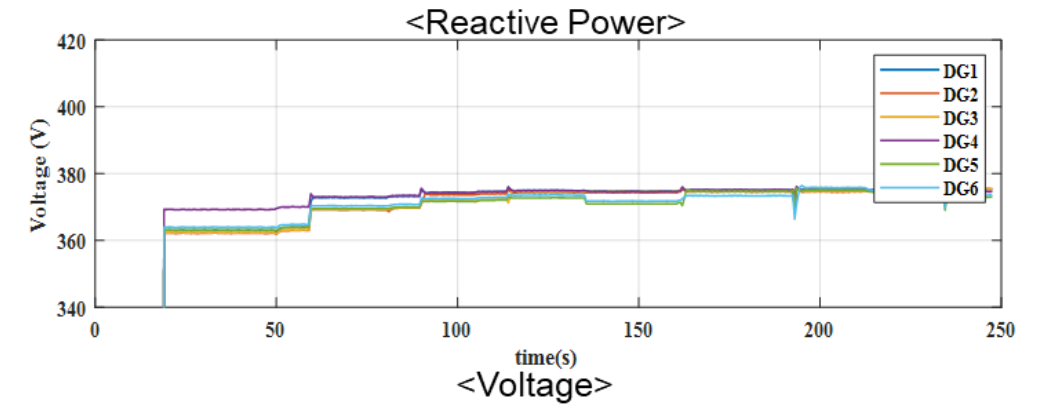
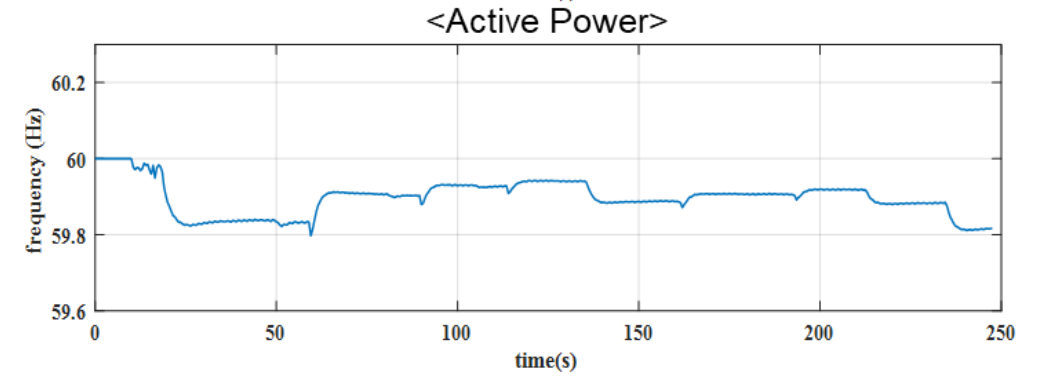
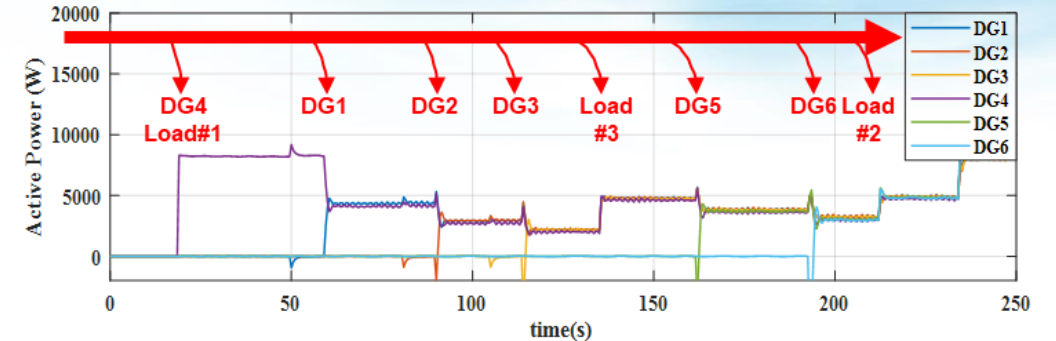
Input	
P	-3.2787592
Q	43.5659981
SOC	69.7629623
P1	13.3673353
Q1	8.2450142
SOC1	69.8814850
P2	0.0000000
Q2	0.0000000
SOC2	0.0000000
Output	
Pref	0.0000000
Qref	0.0000000

Agent6

Input	
P	0.0000000
Q	0.0000000
SOC	0.0000000
P1	-3.2787592
Q1	43.5659981
SOC1	69.7629623
P2	0.0000000
Q2	0.0000000
SOC2	0.0000000
Output	
Pref	0.0000000
Qref	0.0000000



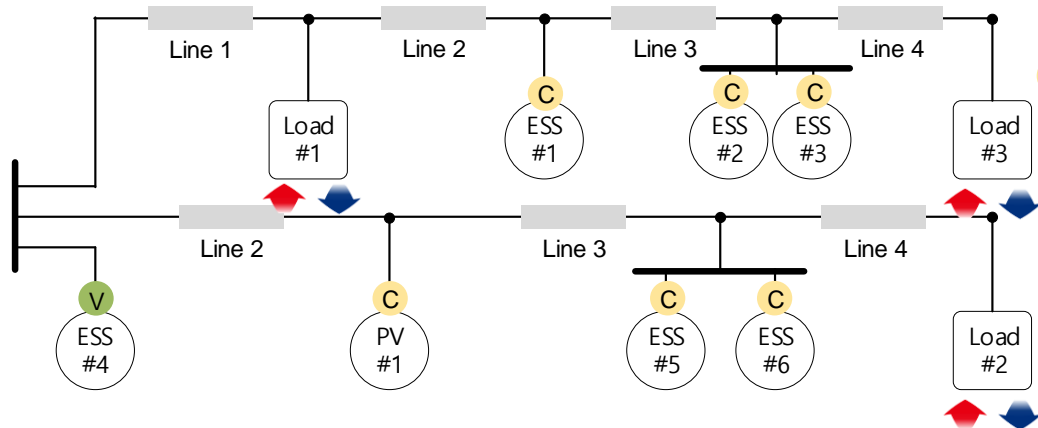
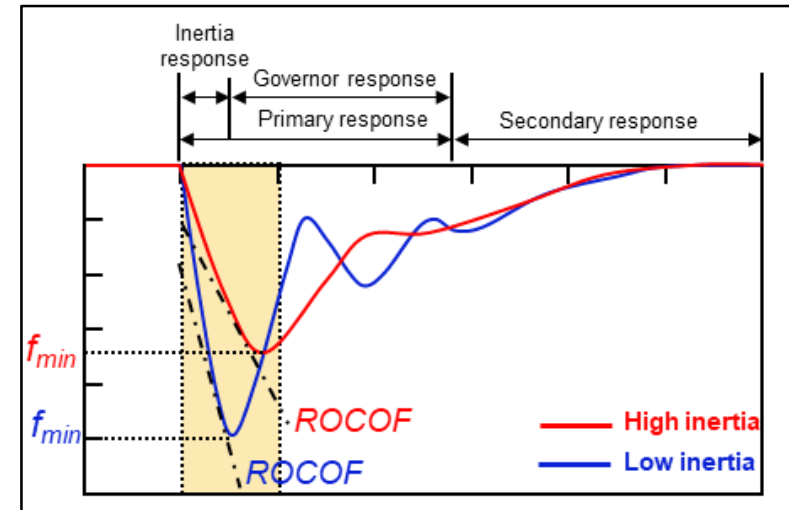
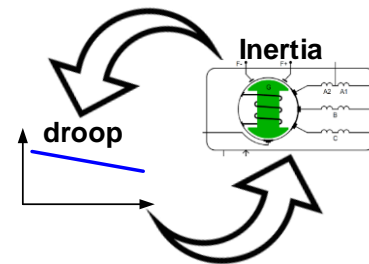
Sequential DG connection



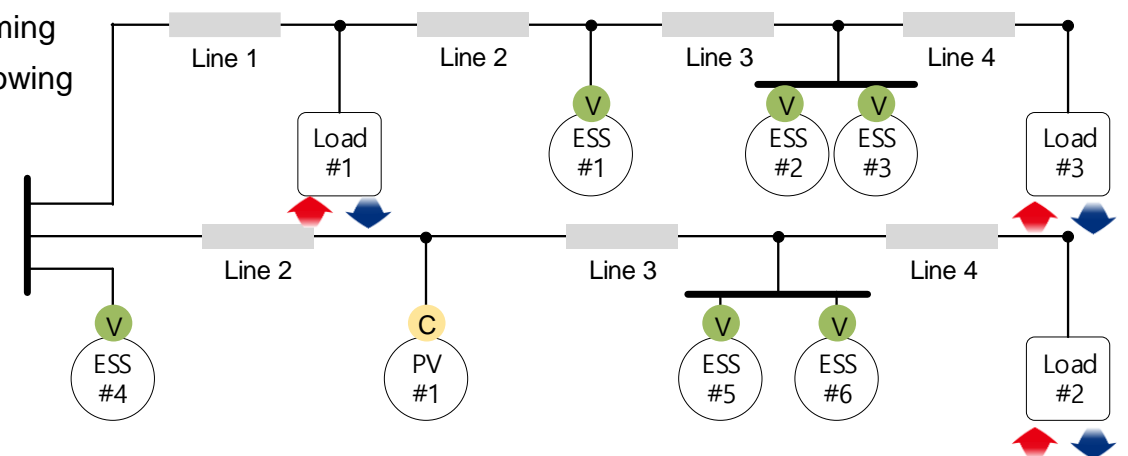
- ❖ Case 0
 - With/without virtual impedance
- ❖ Case 1 (single GFM inverter and the others GFL inverters)
 - Load reduction & increase
 - Single GFM tripping
- ❖ Case 2 (multiple GFM inverters with virtual inertia)
 - Load reduction & increase
 - Single GFM tripping

Check Point

1. Frequency Stability(Nadir, ROCOF)
2. Resiliency(Grid-forming)



V Grid-forming
C Grid-following

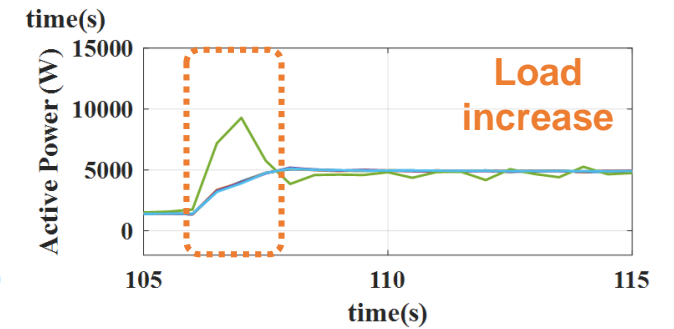
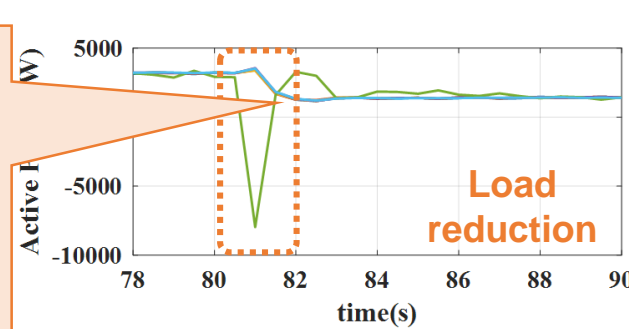
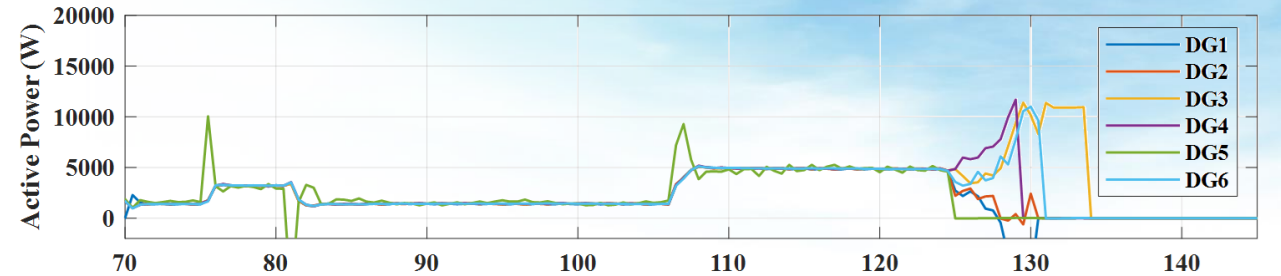
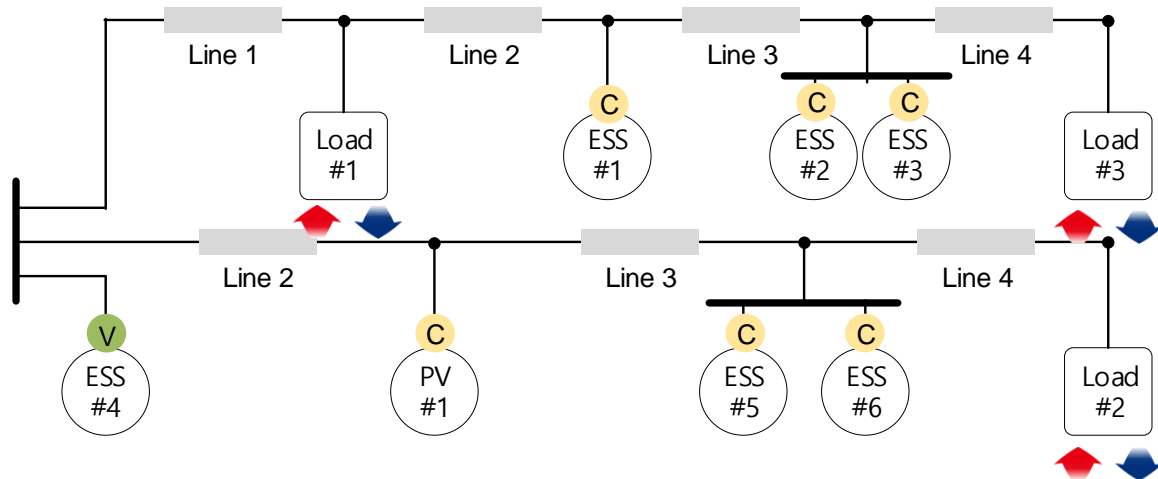


❖ Case1(Scenario)

- ⊖ Load change
- ⊖ GFM inverter tripping

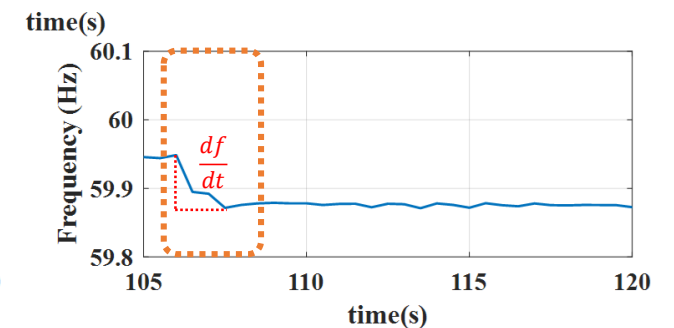
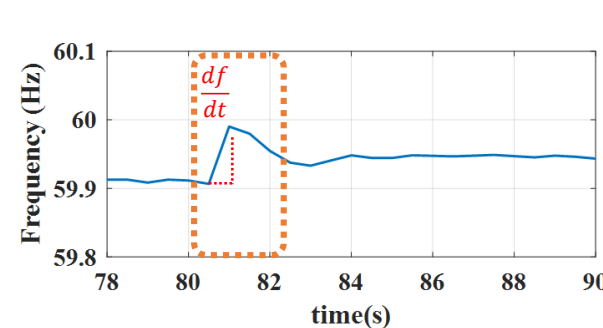
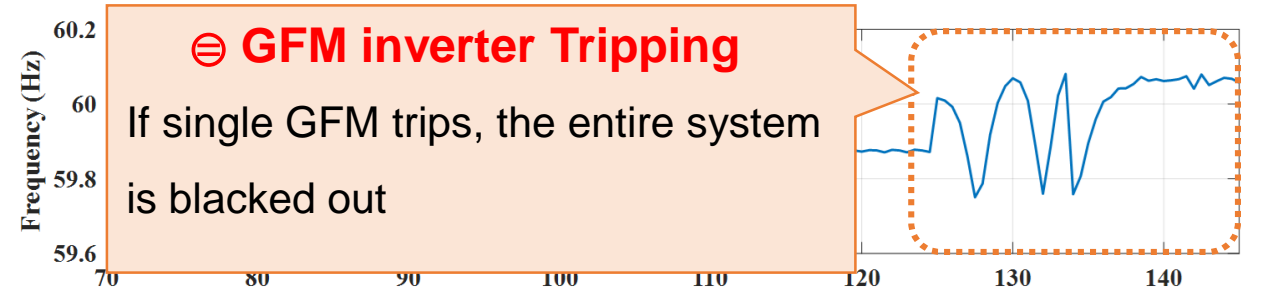
⊖ Load change

- GFM inverter operates first during load change because of the fast responsiveness of the GFM inverter



⊖ GFM inverter Tripping

If single GFM trips, the entire system is blacked out

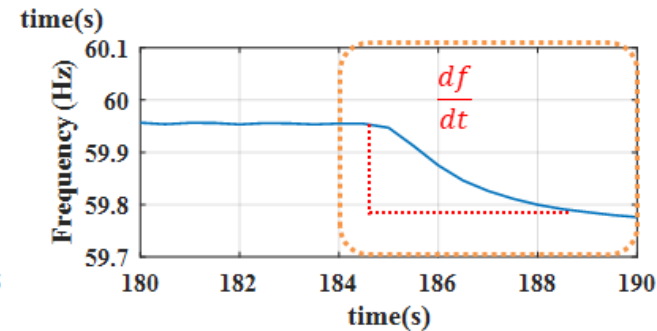
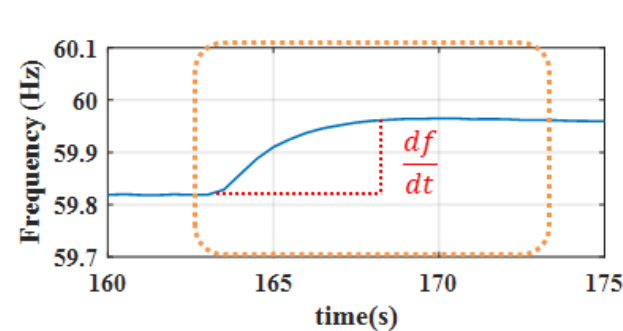
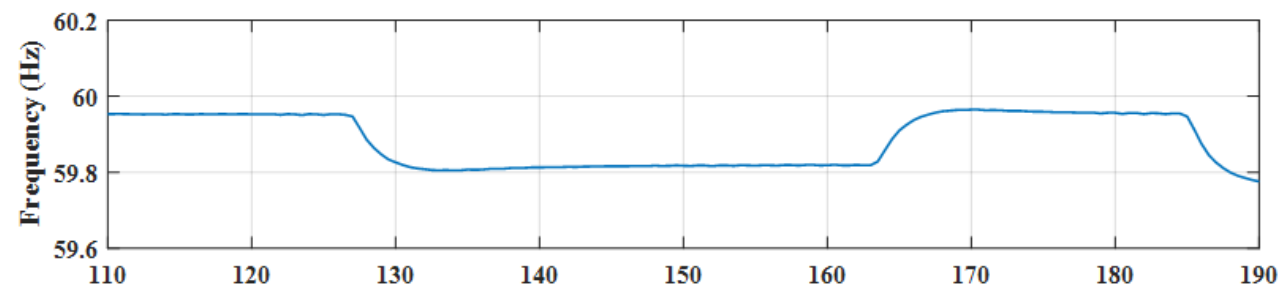
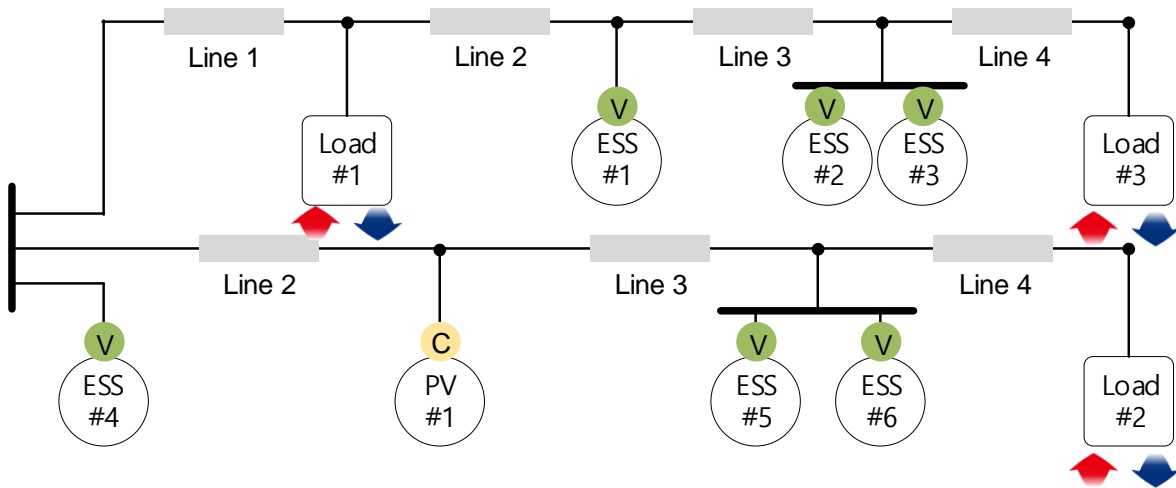
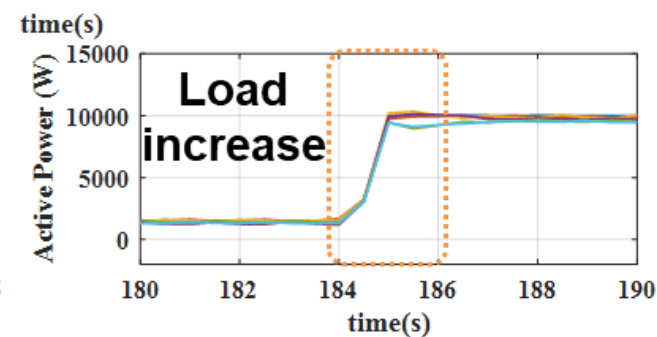
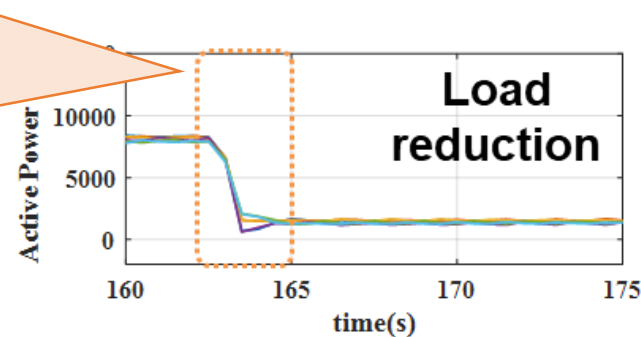
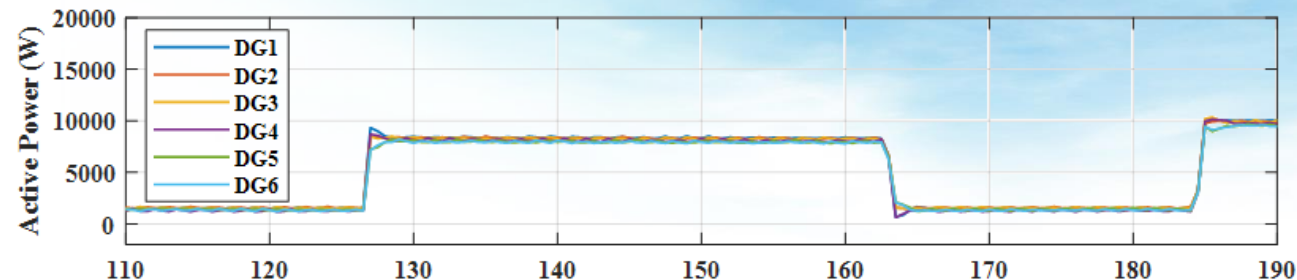


❖ Case2(Scenario)

⊖ Load change

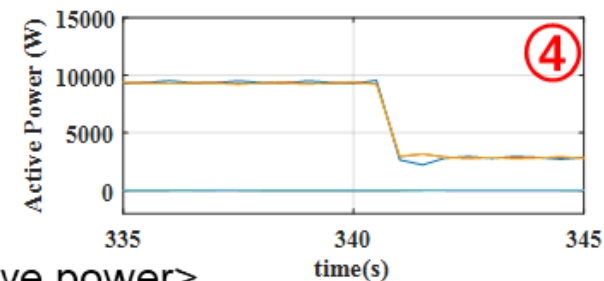
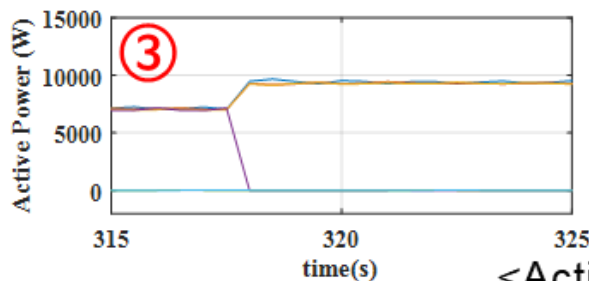
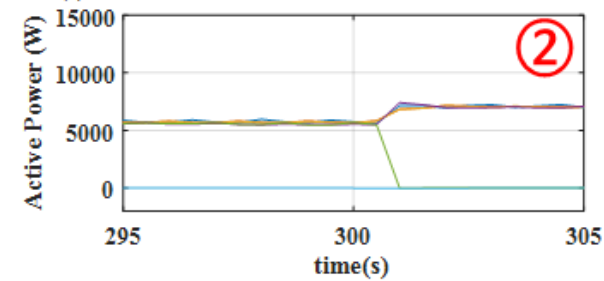
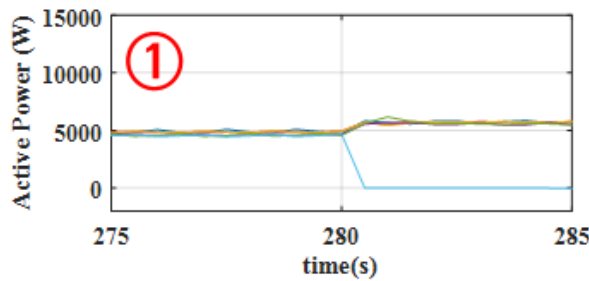
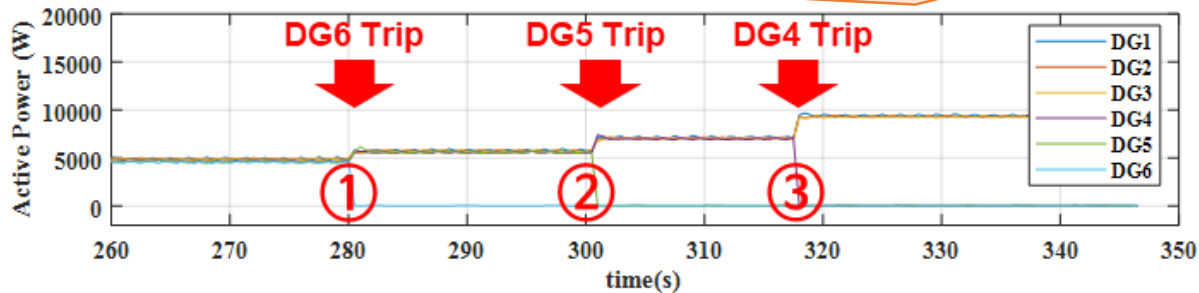
Load change

- The frequency is controlled stably, because all GFM inverters operate at similar response time during load change,

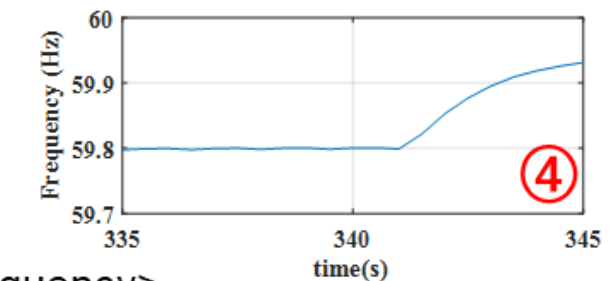
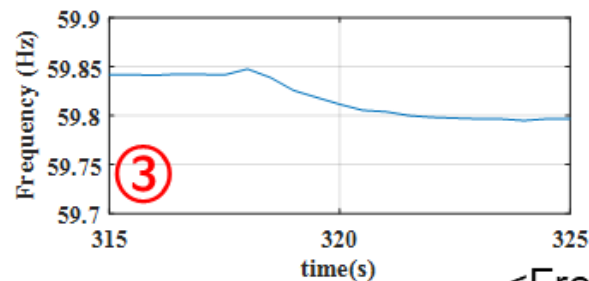
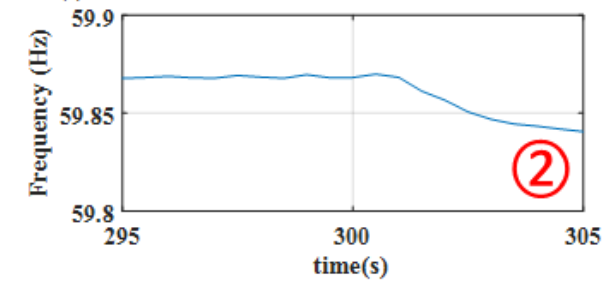
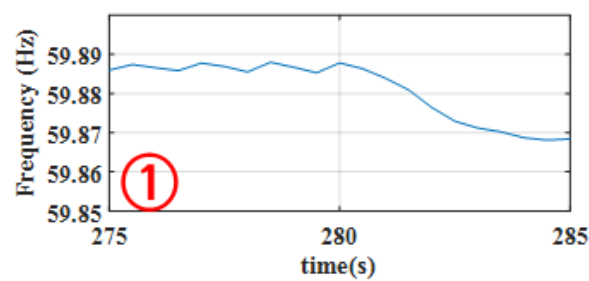
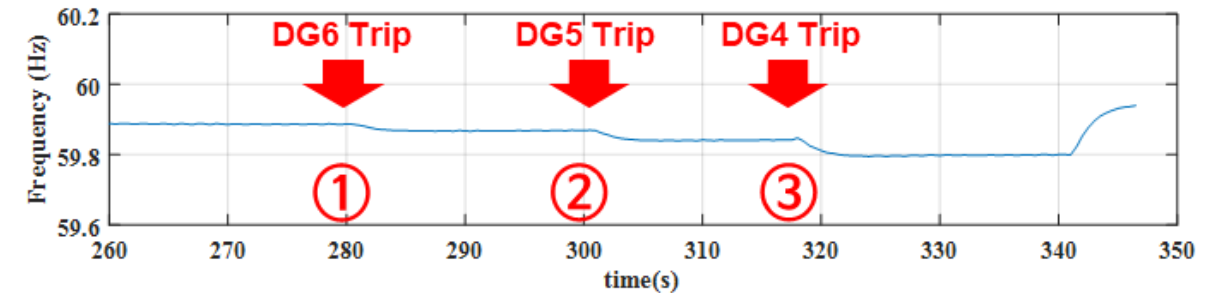


❖ GFM inverter-based DG trip

- Scenario : The load amount is the same and DG is tripped sequentially
- The frequency and voltage can be maintained even if some DG trips because voltage is generated from multiple voltage sources.



<Active power>



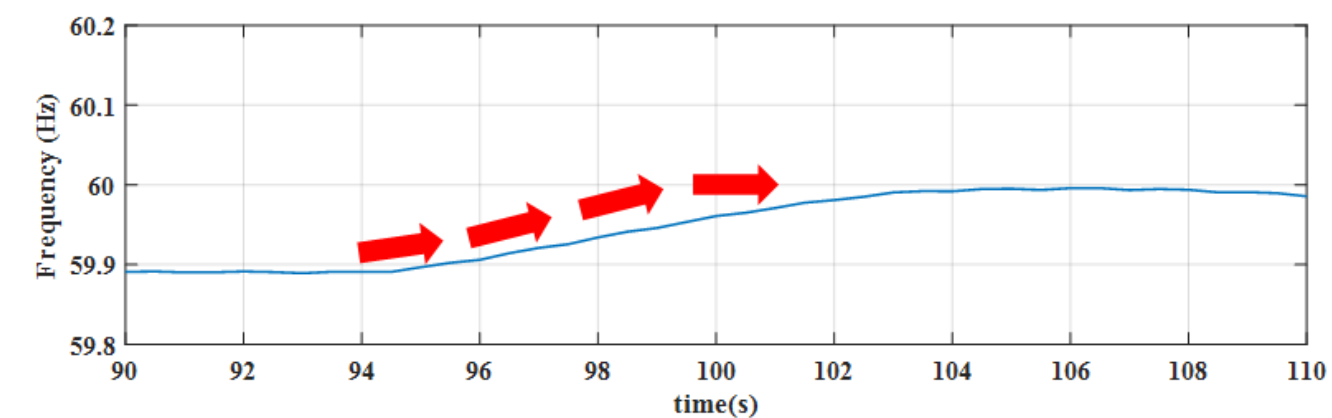
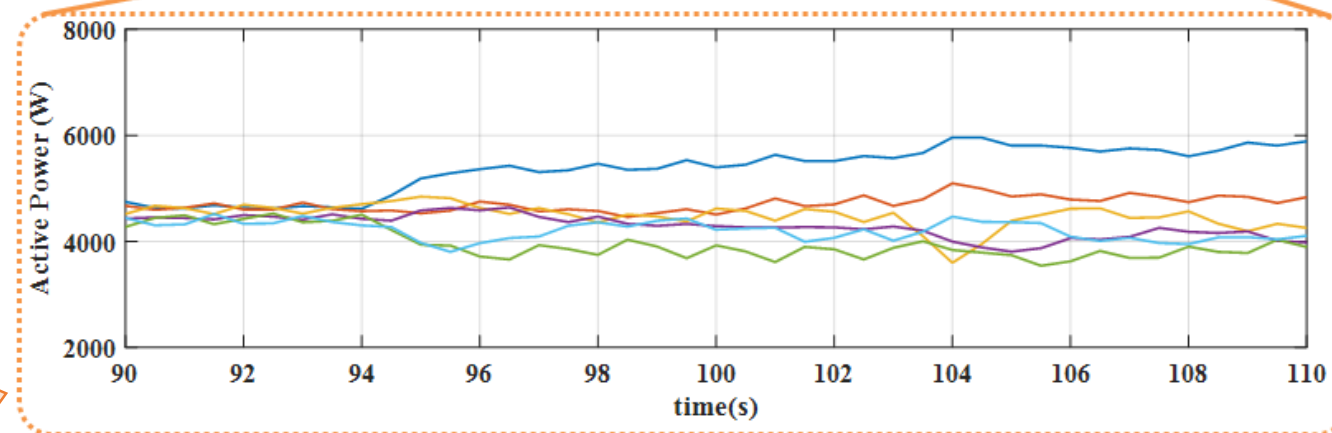
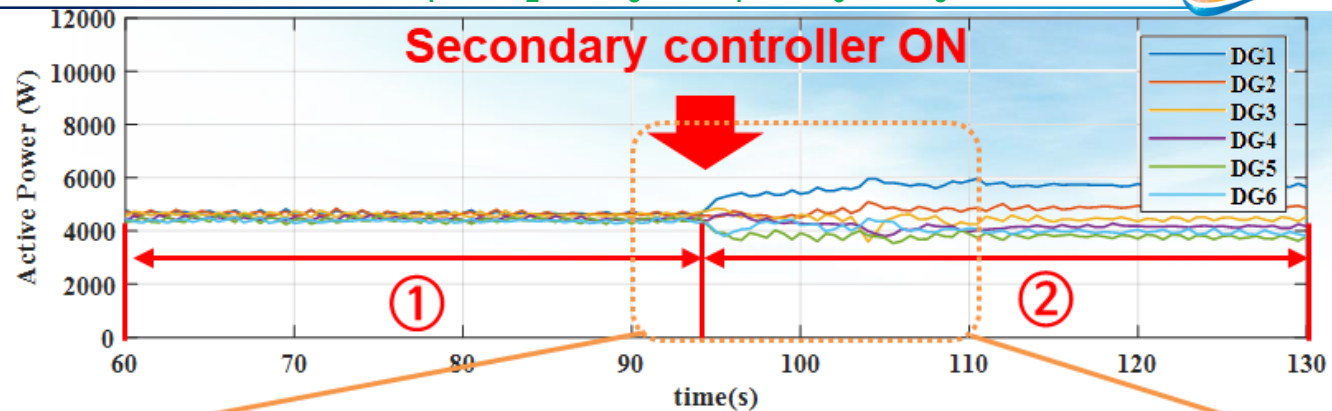
<Frequency>

Test Results – Distributed operation function

Incremental cost
 $DG_1 < DG_2 < DG_3 < DG_4 < DG_6 < DG_5$



No.	A_i (\$/KW ₂ H)	β_i (\$/kWh)
DG ₁	0.001562	3.82
DG ₂	0.00174	3.99
DG ₃	0.00186	4.15
DG ₄	0.00196	4.53
DG ₅	0.00208	5.09
DG ₆	0.00219	3.11



⊖ **Section:** only primary controller operates
 ⊖ **Section:** Secondary controller ON
 - Active power output change according to the incremental cost of each IBR



Development of Advanced Microgrid Technology

Phase1

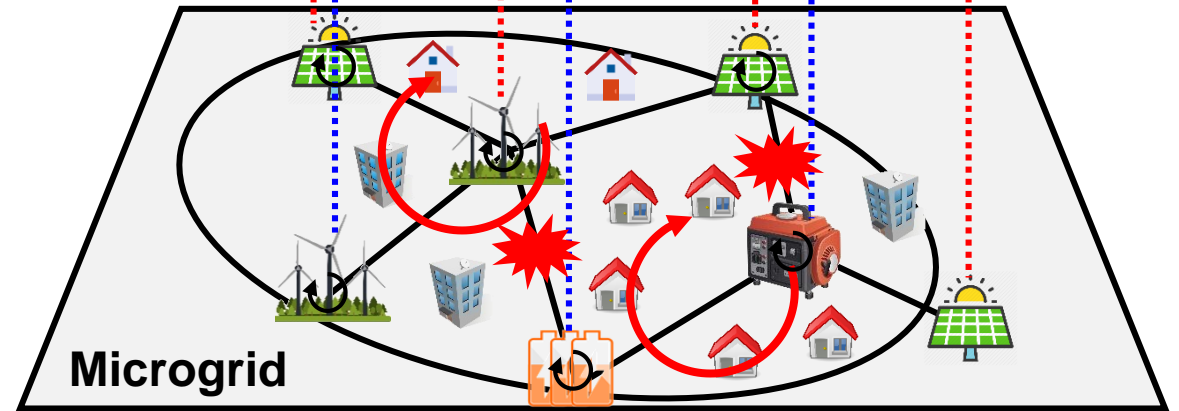
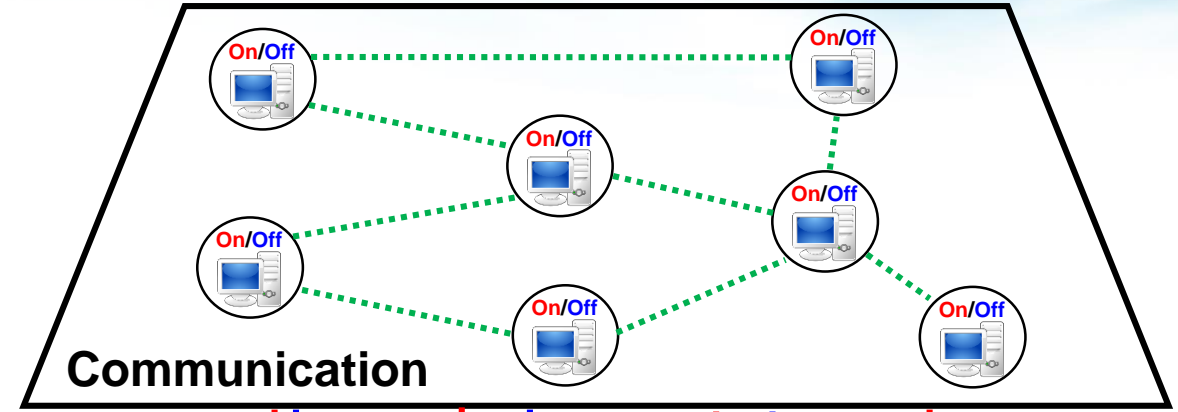
Autonomous Operation
using distributed strategy

Phase2

Autonomous restorative &
self healing/auto
configuration



Self healing
Auto configuration



Distributed Power System Research Center

Thank you

